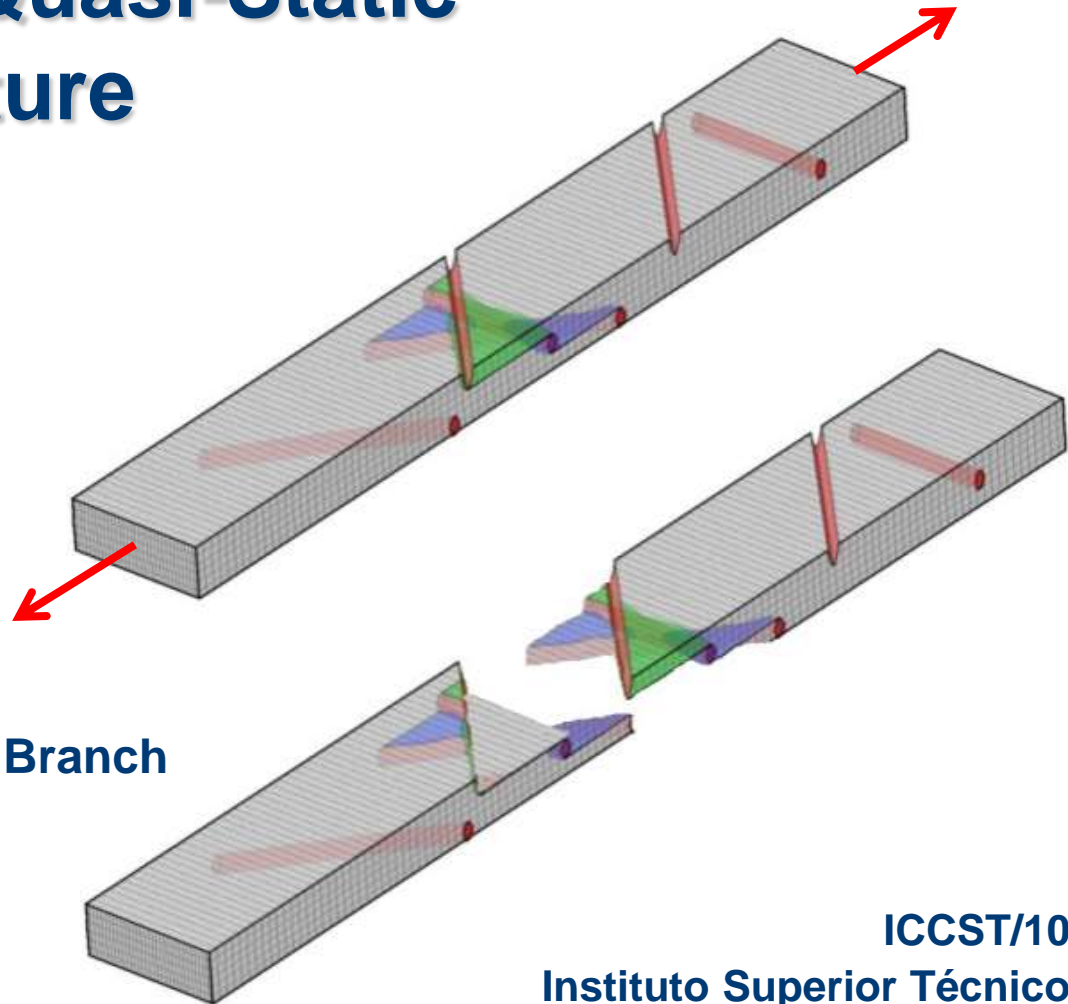




Damage Instability and Transition from Quasi-Static to Dynamic Fracture

Carlos G. Dávila

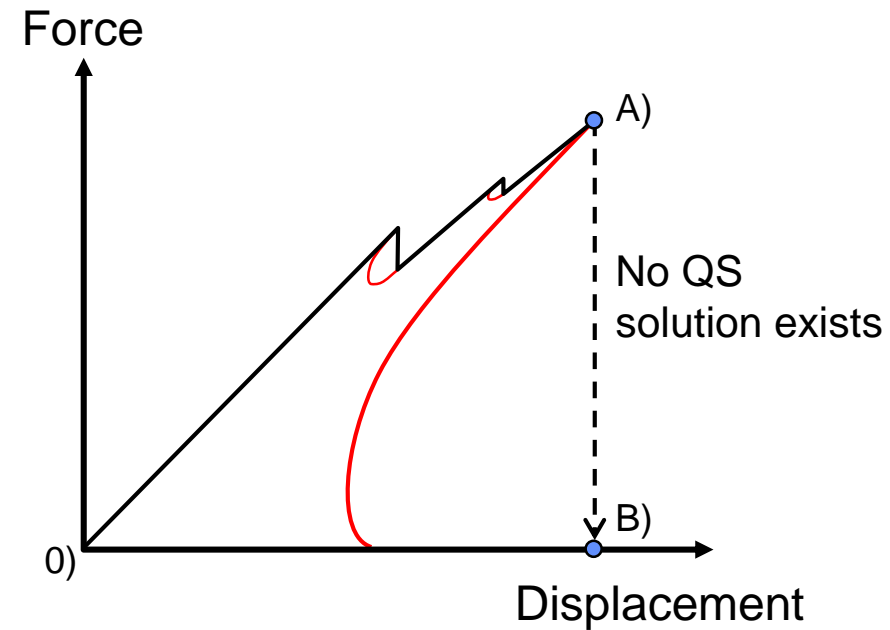
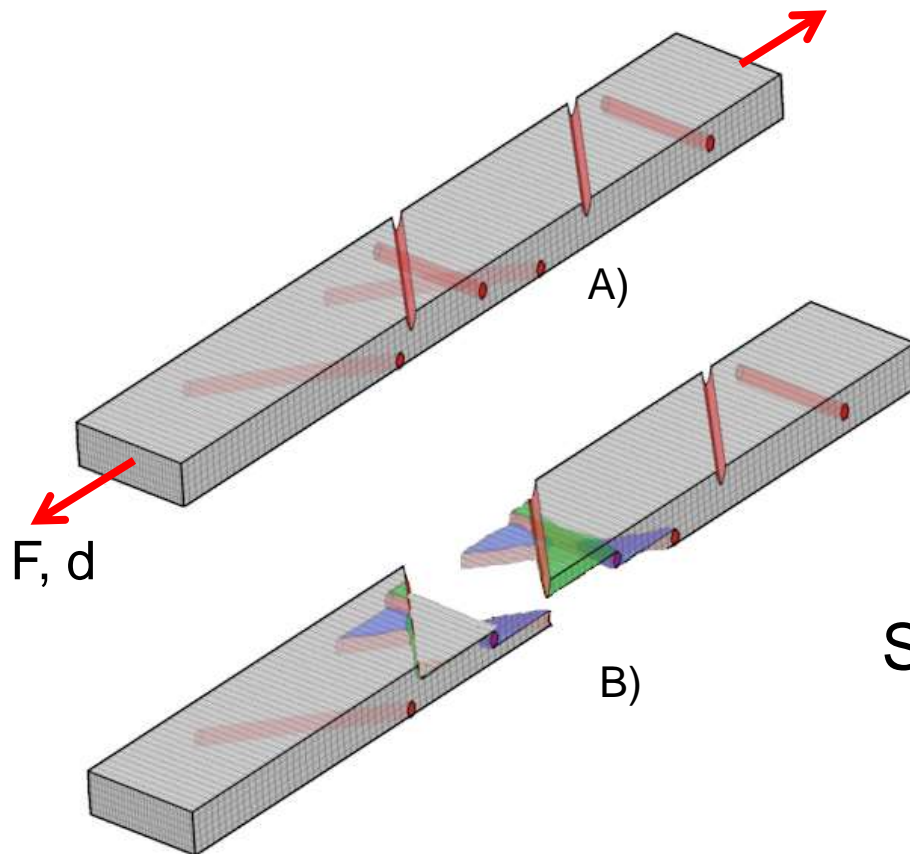
**Structural Mechanics & Concepts Branch
NASA Langley Research Center
Hampton, VA
USA**



**ICCST/10
Instituto Superior Técnico
Lisbon, Portugal, 2-4 September 2015**

Loading Phases:

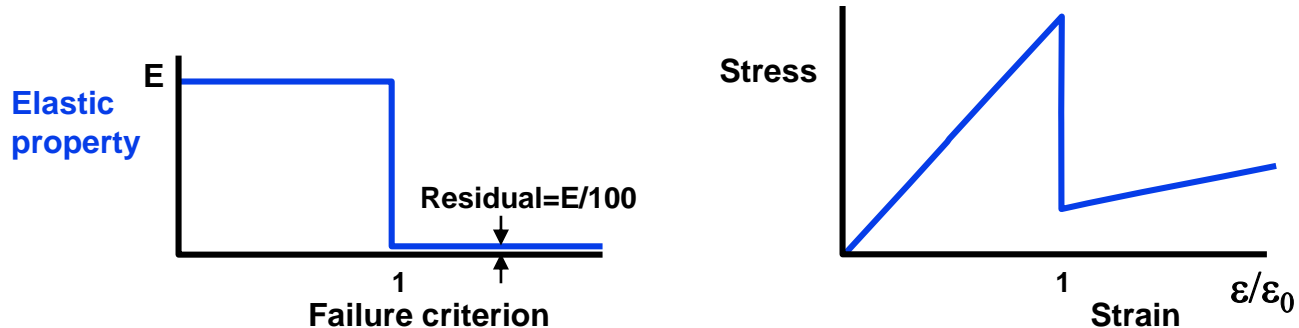
- 0) to A) – Quasi-static (QS) loading
- A) to B) – Dynamic response



Snapback behavior:

- More strain energy available than necessary for fracture

Progressive Failure Analysis



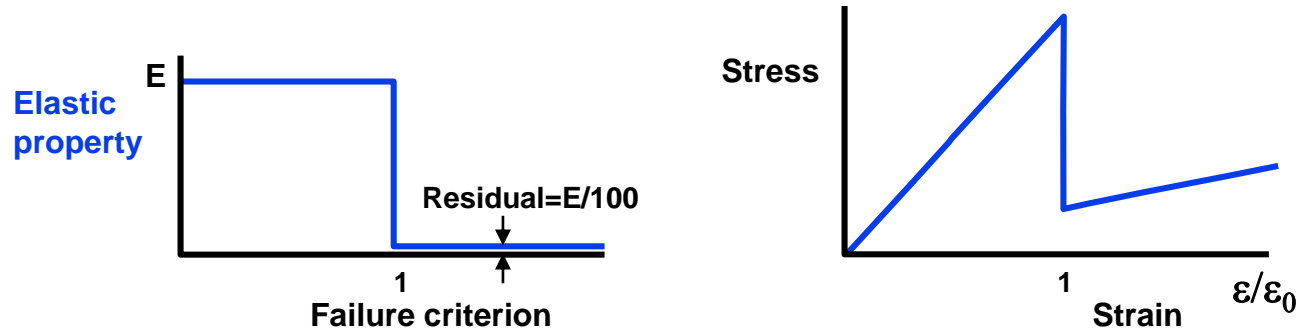
Benefits

- Simplicity (no programming needed)
- Convergence of equilibrium iterations

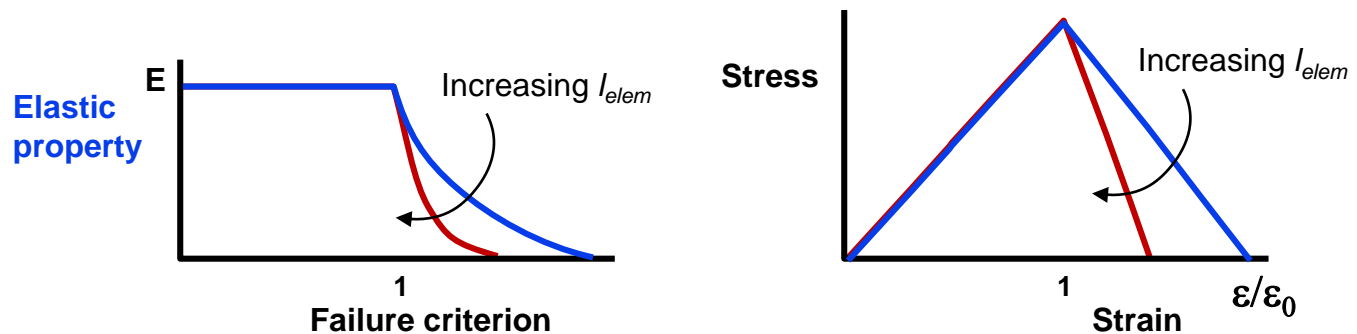
Drawbacks

- Mesh dependence
- Dependence on load increment
- Ad-hoc property degradation
- Large strains can cause reloading
- Errors due to improper load redistributions

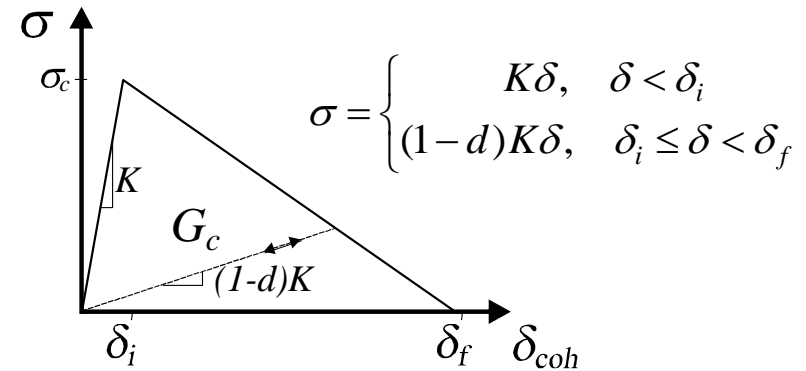
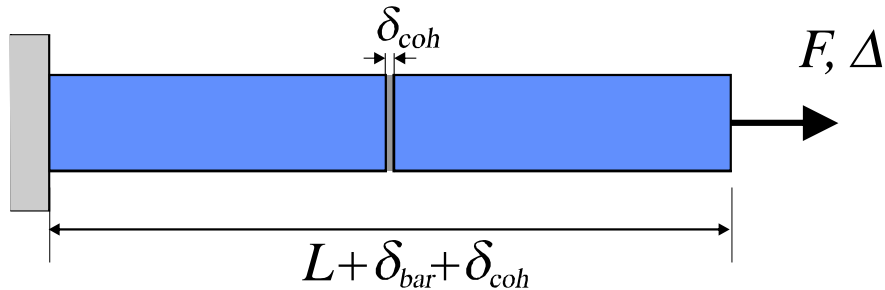
Progressive Failure Analysis



Progressive Damage Analysis – Regularized Softening Laws



Strength-Dominated Failure

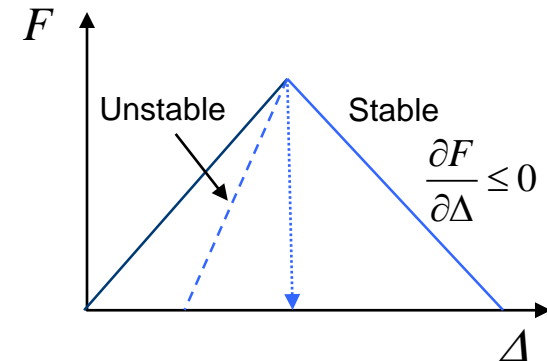


Before damage

$$F = A\sigma = EA \frac{\Delta}{L + \frac{E}{K}}$$

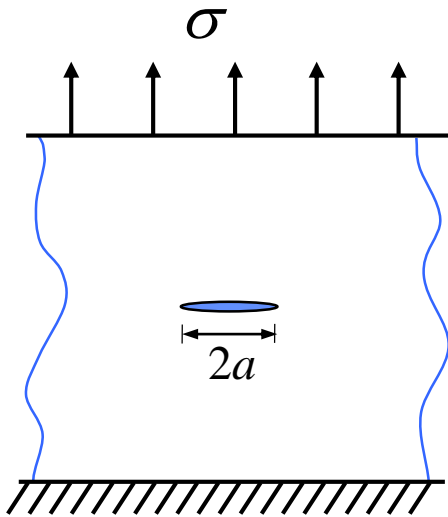
After damage

$$F = A\sigma = EA \frac{\Delta - \frac{2G_c}{\sigma_c}}{L - \frac{2EG_c}{\sigma_c^2} + \frac{E}{K}}$$

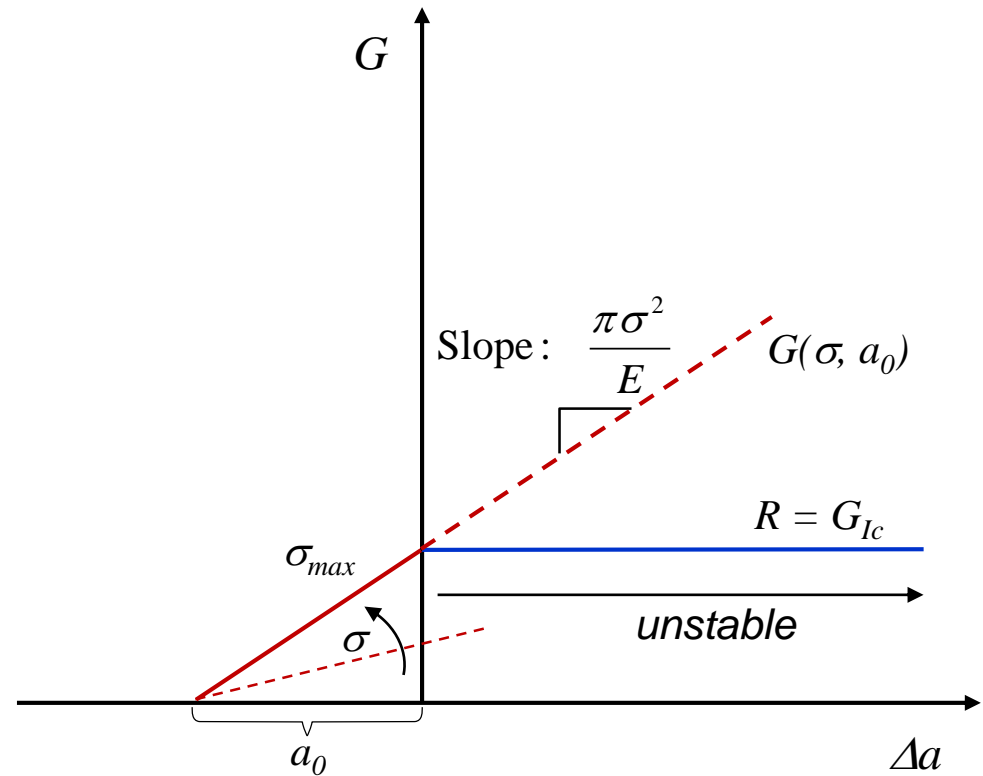


For stable fracture under Δ control: $\frac{\partial F}{\partial \Delta} \leq 0 \Rightarrow \boxed{L \leq \frac{2EG_c}{\sigma_c^2}}$

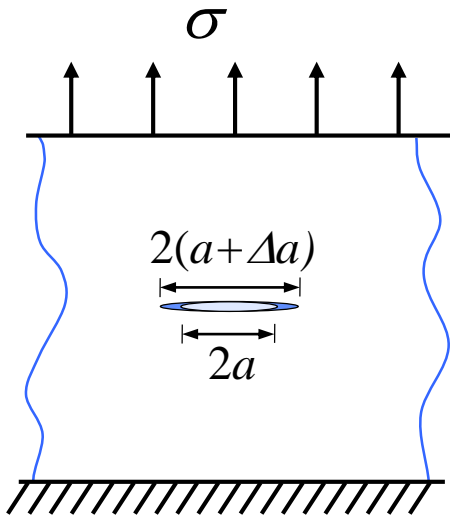
For “long” beams, the response is unstable, dynamic, and independent of G_c



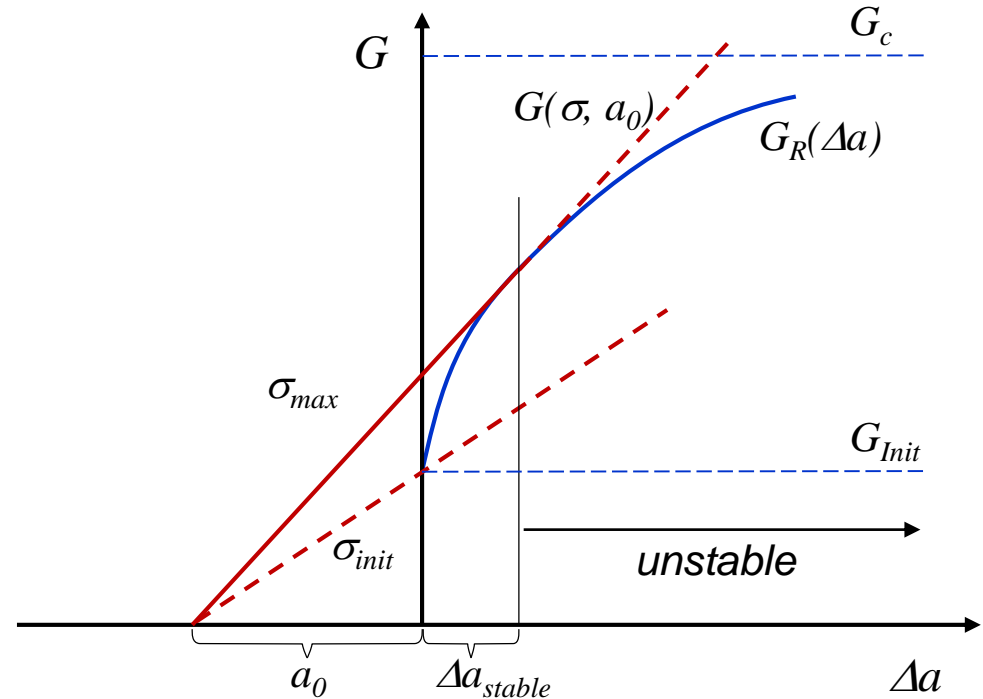
$$G = \frac{\pi \sigma^2 a}{E}$$



Crack propagates unstably once driving force $G(\sigma, a_0)$ reaches G_{Ic}

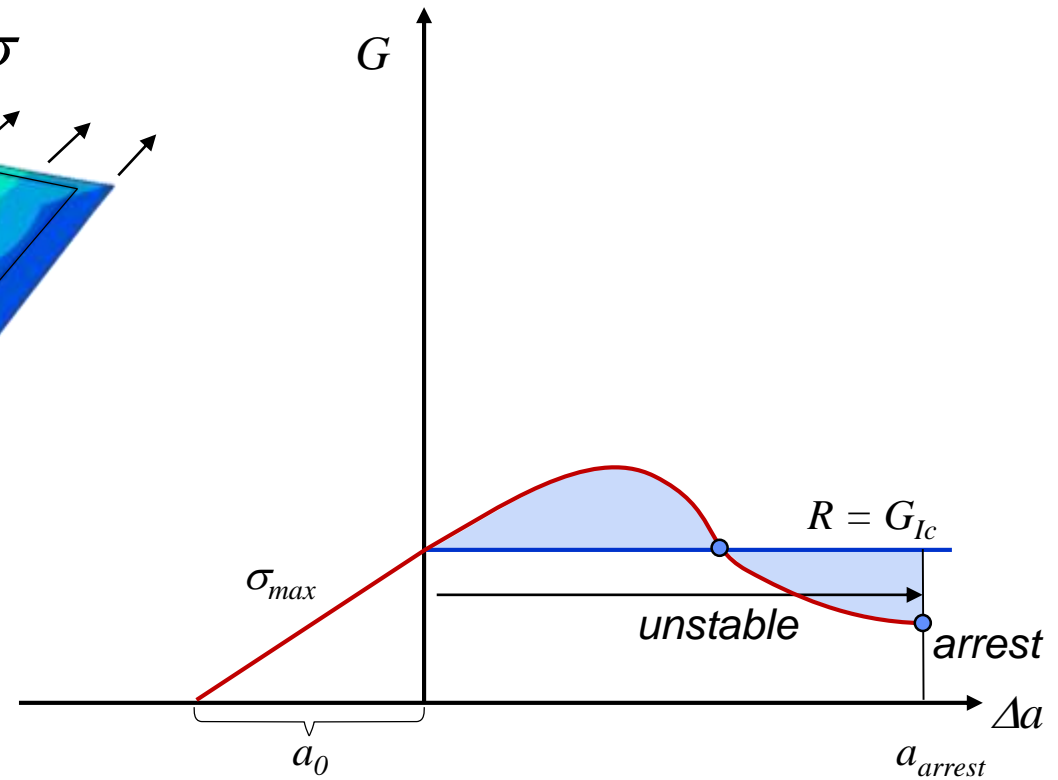
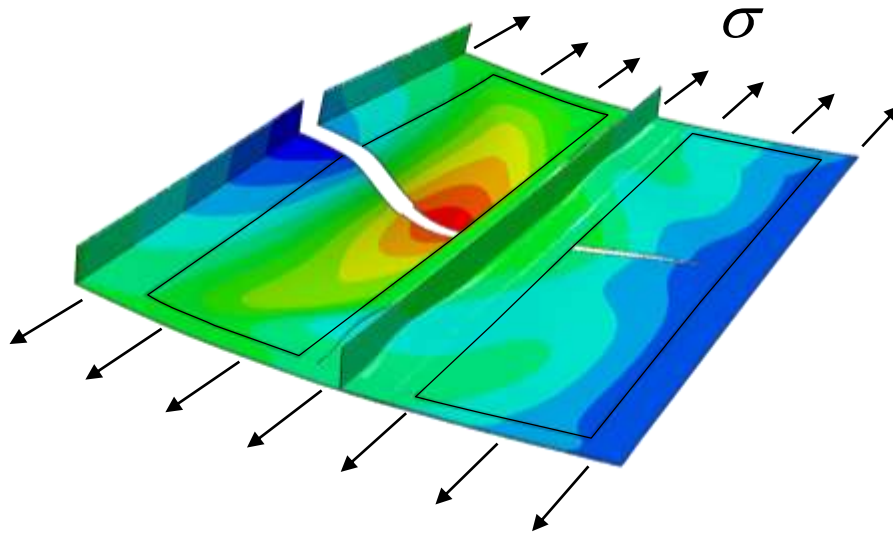


$$G = \frac{\pi \sigma^2 a}{E}$$

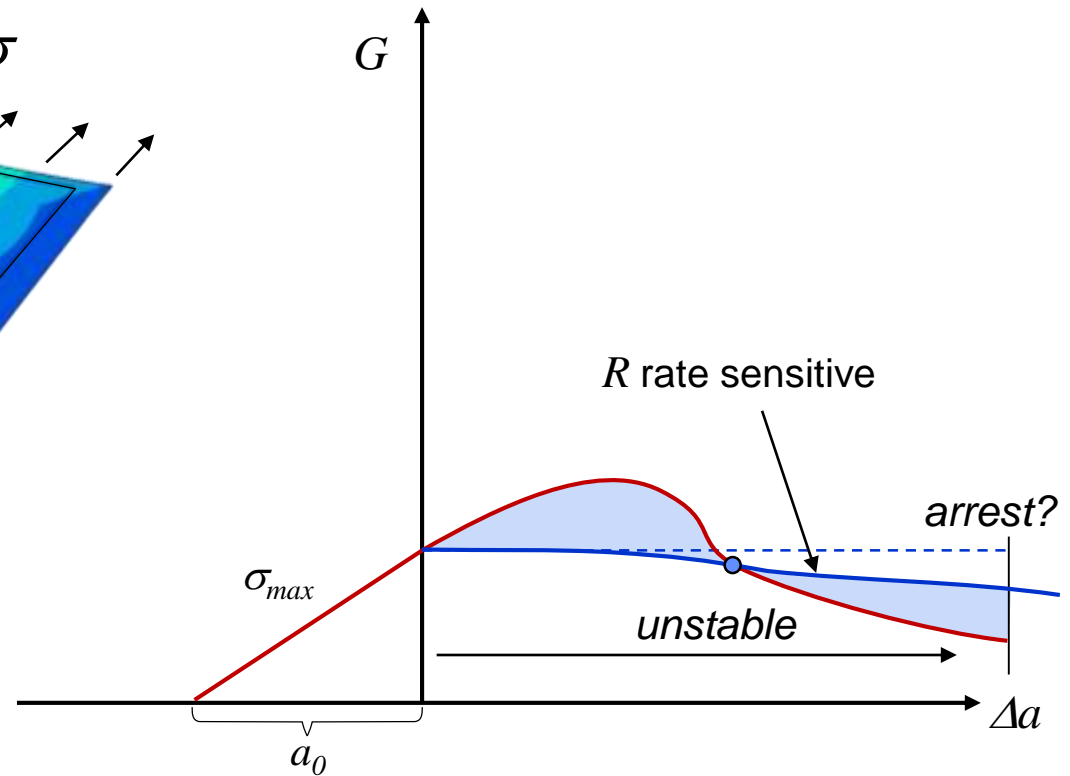
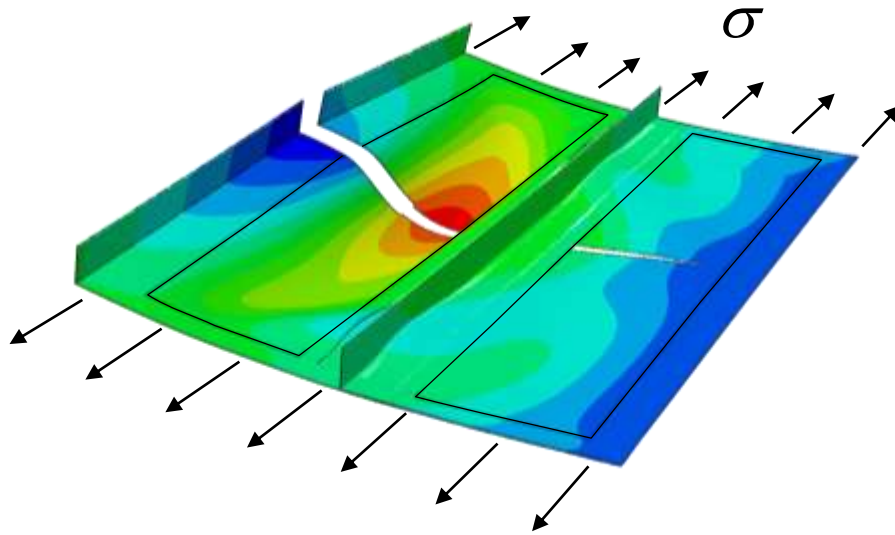


Crack propagates stably when driving force $G(\sigma, a_0) > G_{Init}$

Unstable propagation initiates at $G_{Init} < G \leq G_c$



Crack arrest due to decreasing G



Large strain rates often result in lower fracture toughness and delayed arrest

Griffith growth criterion

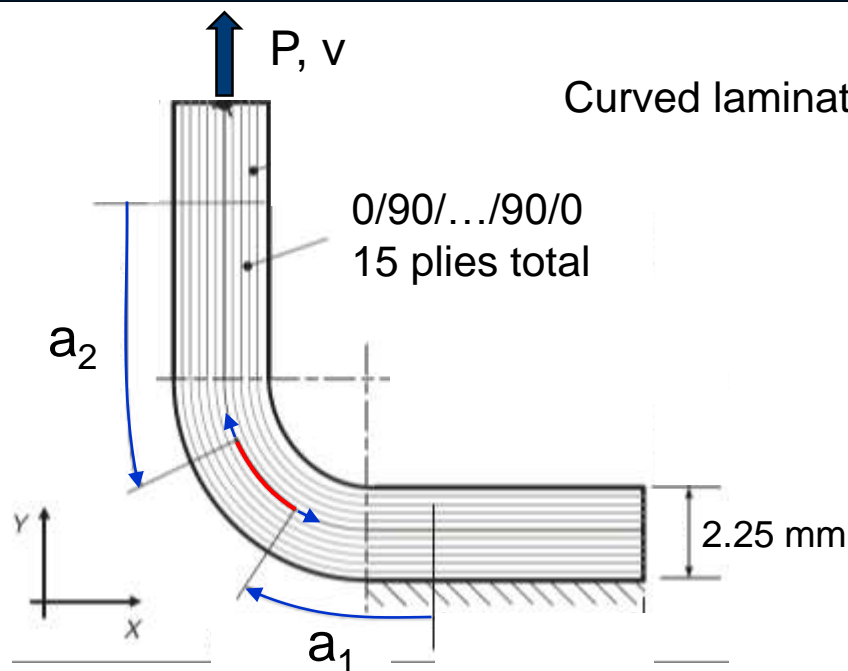
$$\frac{\partial \Pi_{\text{total}}}{\partial a_i} = \frac{\partial (\Pi_{\text{int}} + \Pi_{\text{ext}})}{\partial a_i} + G_{c,i} = \begin{cases} > 0 & \text{no growth} \\ 0 & \text{equilibrium growth} \\ < 0 & \text{dynamic growth} \end{cases}$$

Stability of equilibrium propagation

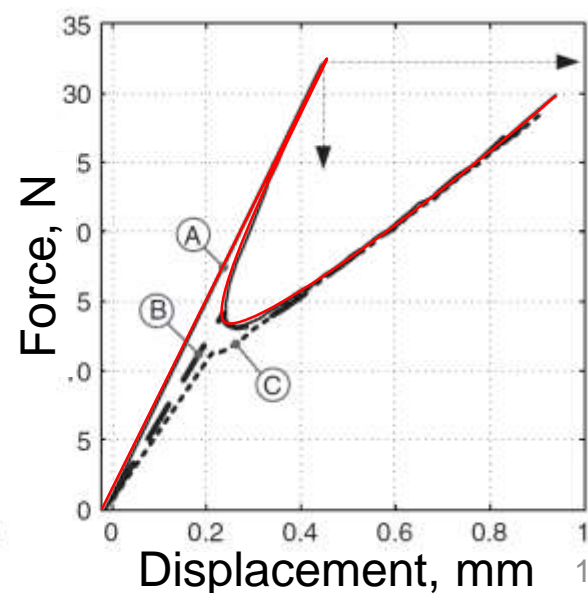
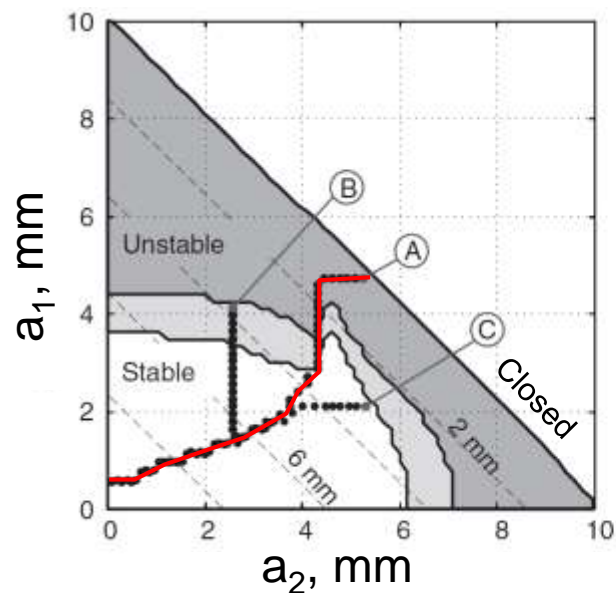
$$\frac{\partial^2 \Pi_{\text{total}}}{\partial a_i^2} = \begin{cases} > 0 & \text{stable} \\ < 0 & \text{unstable} \end{cases}$$

Wimmer & Pettermann
J of Comp. Mater, 2009

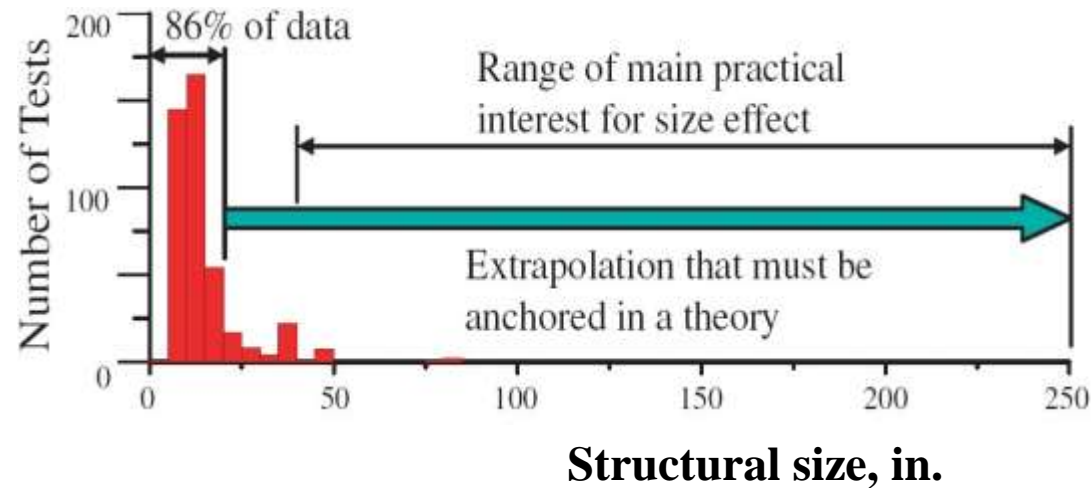
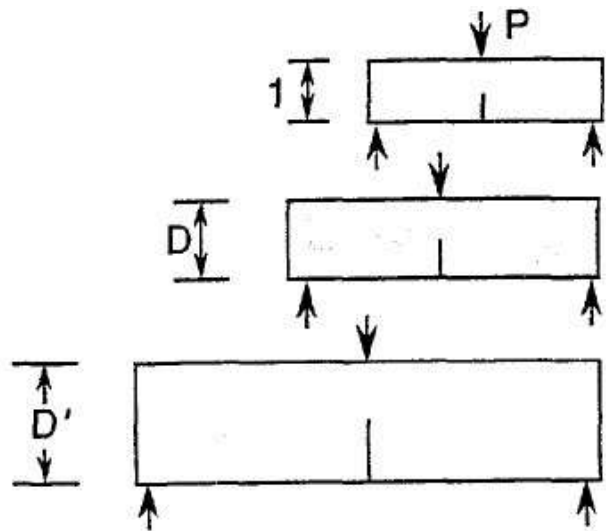
Stability of Propagation with Multiple Crack Tips



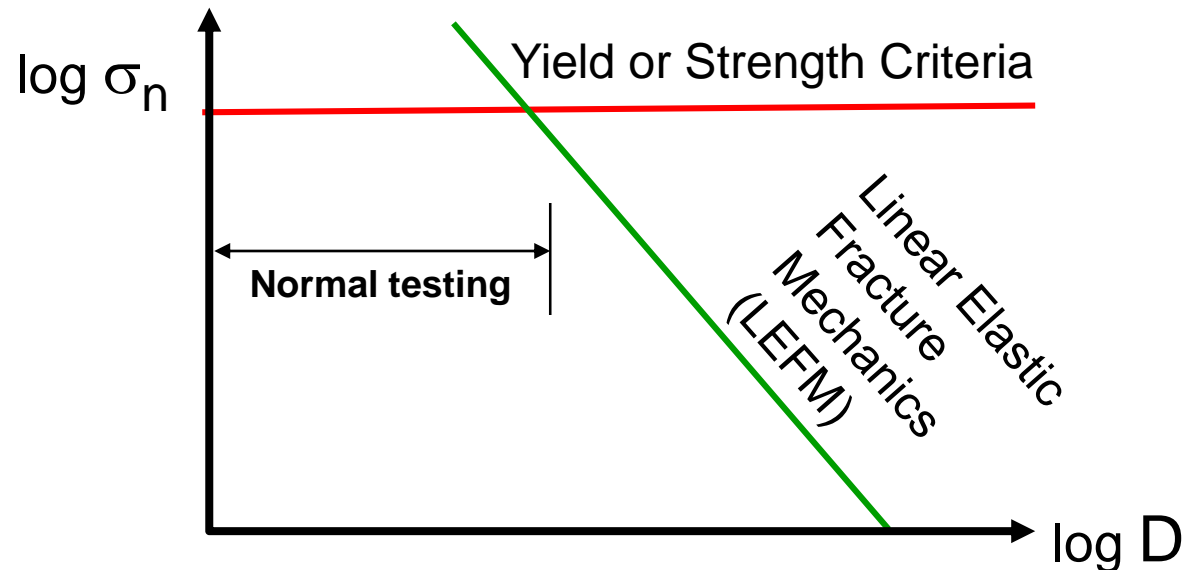
$$\frac{\partial^2 \Pi_{\text{total}}}{\partial a_i^2} = \begin{cases} > 0 & \text{stable} \\ < 0 & \text{unstable} \end{cases}$$

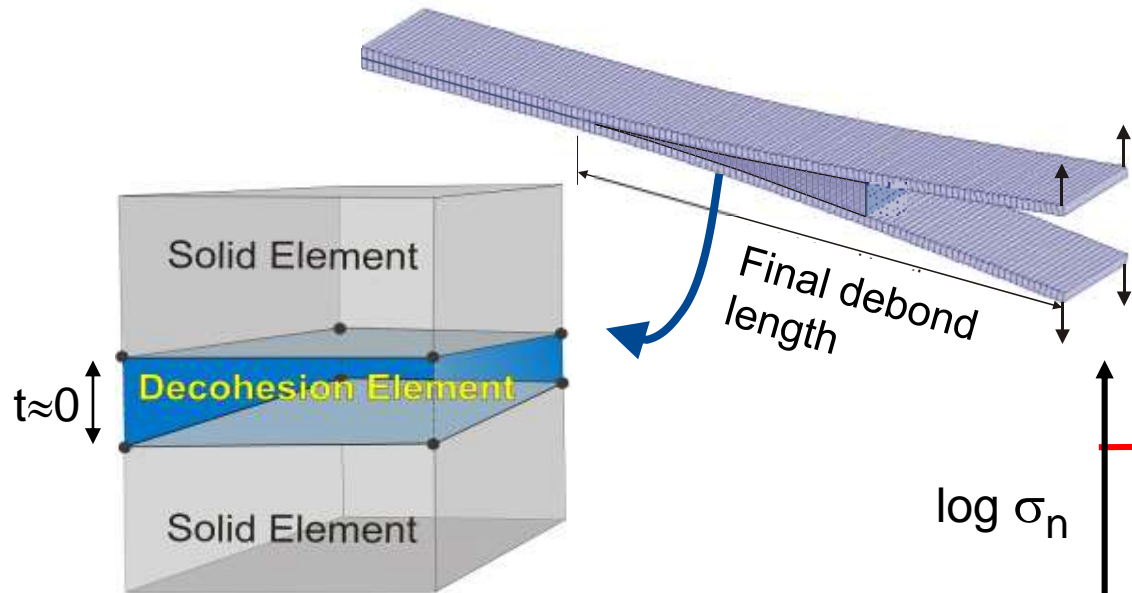


Scaling from test coupon to structure



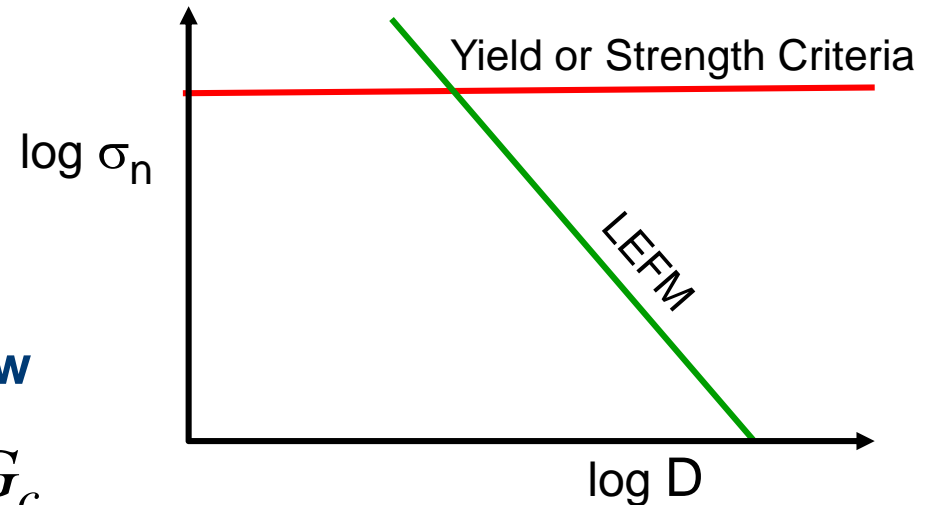
Scaling Laws (Z. Bažant)



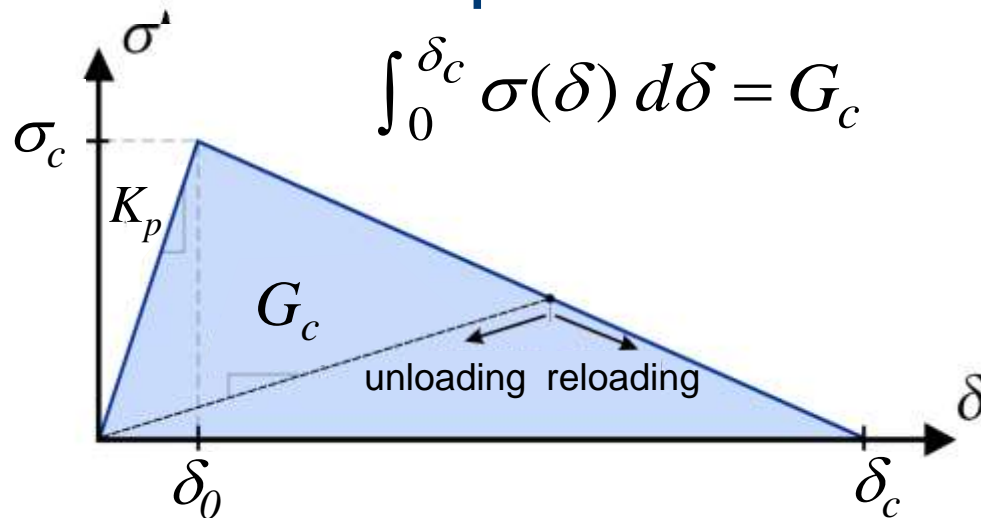


Two material properties:

- G_c Fracture toughness
- σ_c Strength



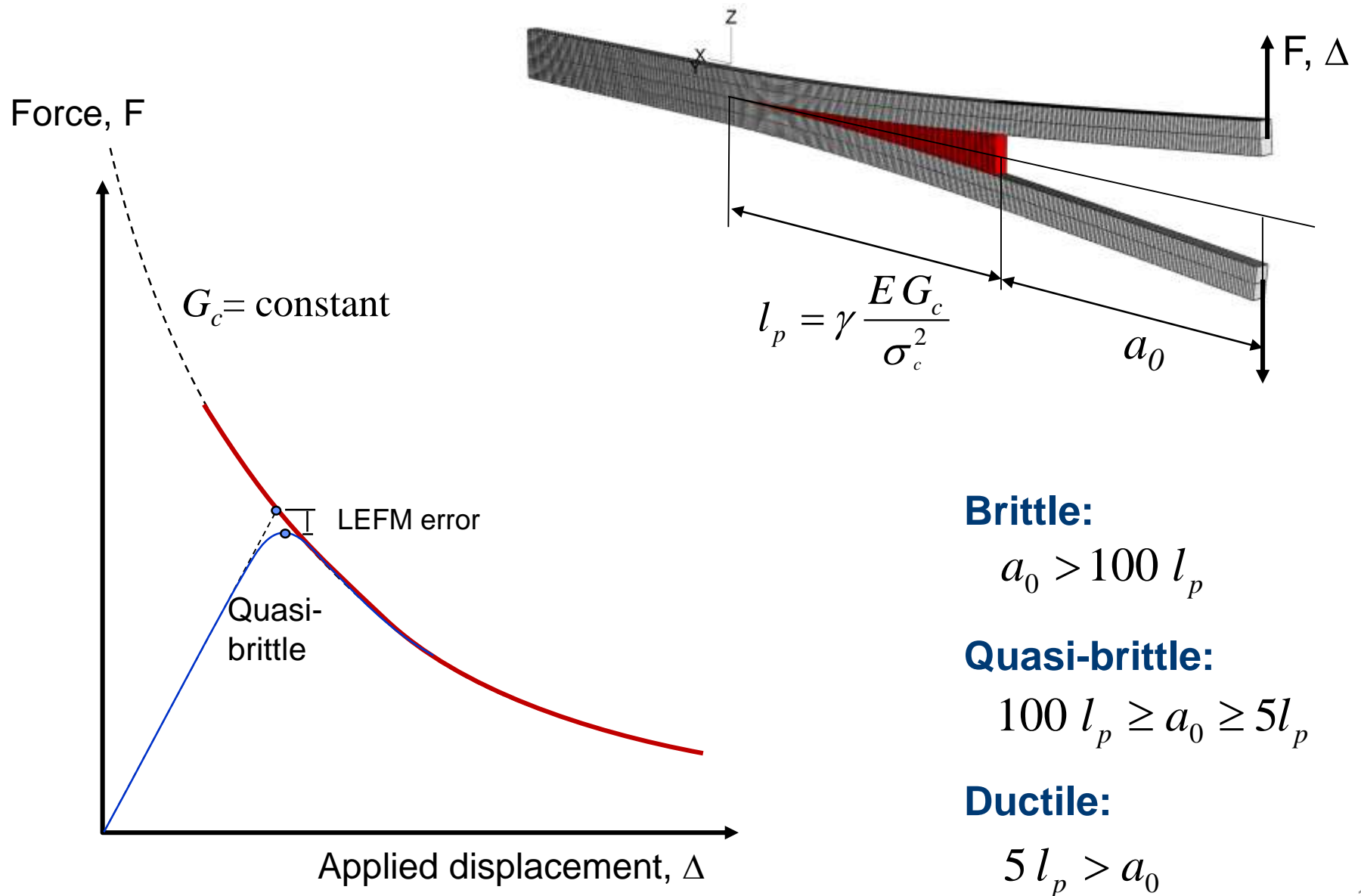
Bilinear Traction-Displacement Law



Characteristic Length:

$$l_p = \gamma \frac{E G_c}{\sigma_c^2}$$

Crack Length and Process Zone



Brittle:

$$a_0 > 100 l_p$$

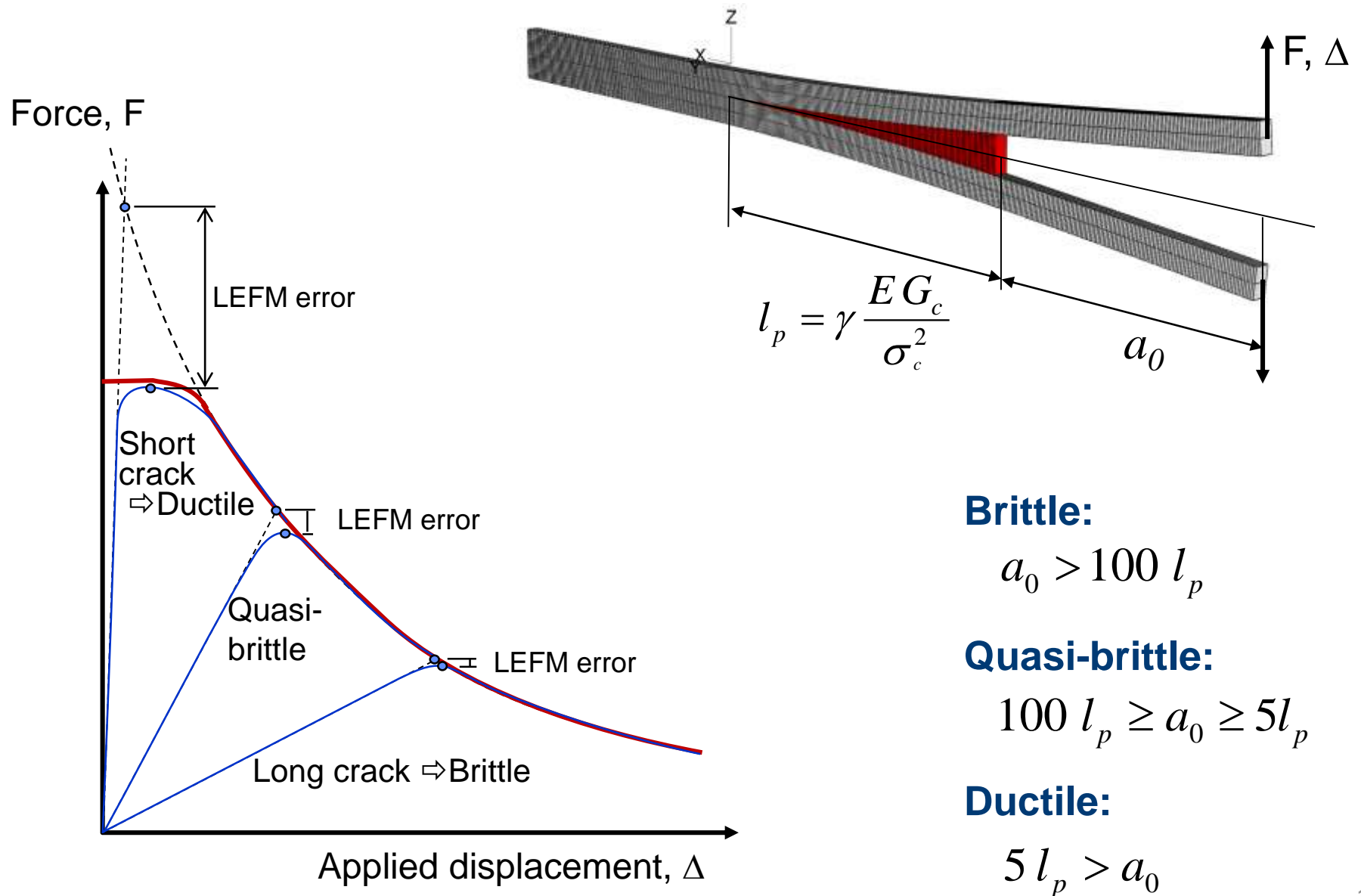
Quasi-brittle:

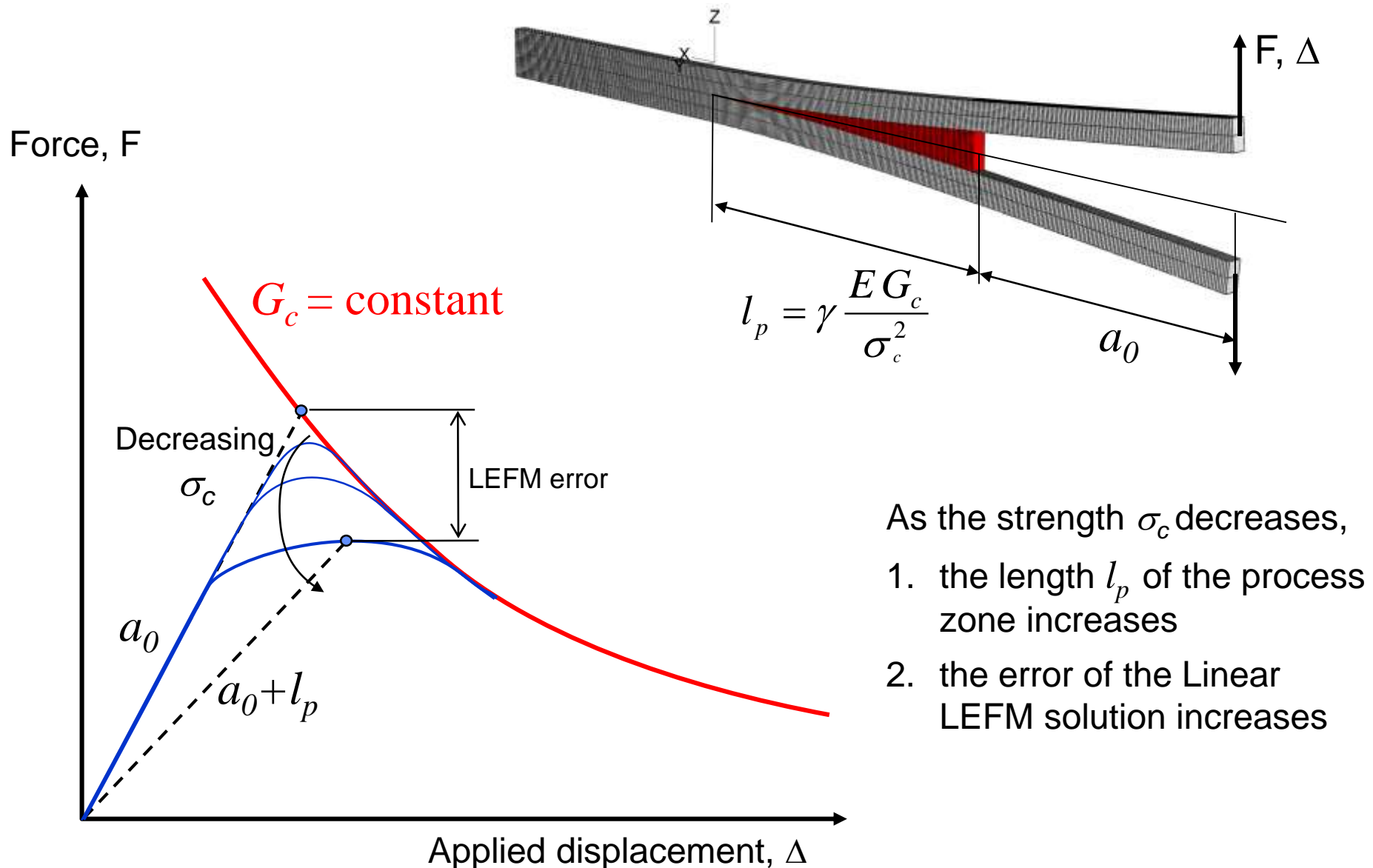
$$100 l_p \geq a_0 \geq 5 l_p$$

Ductile:

$$5 l_p > a_0$$

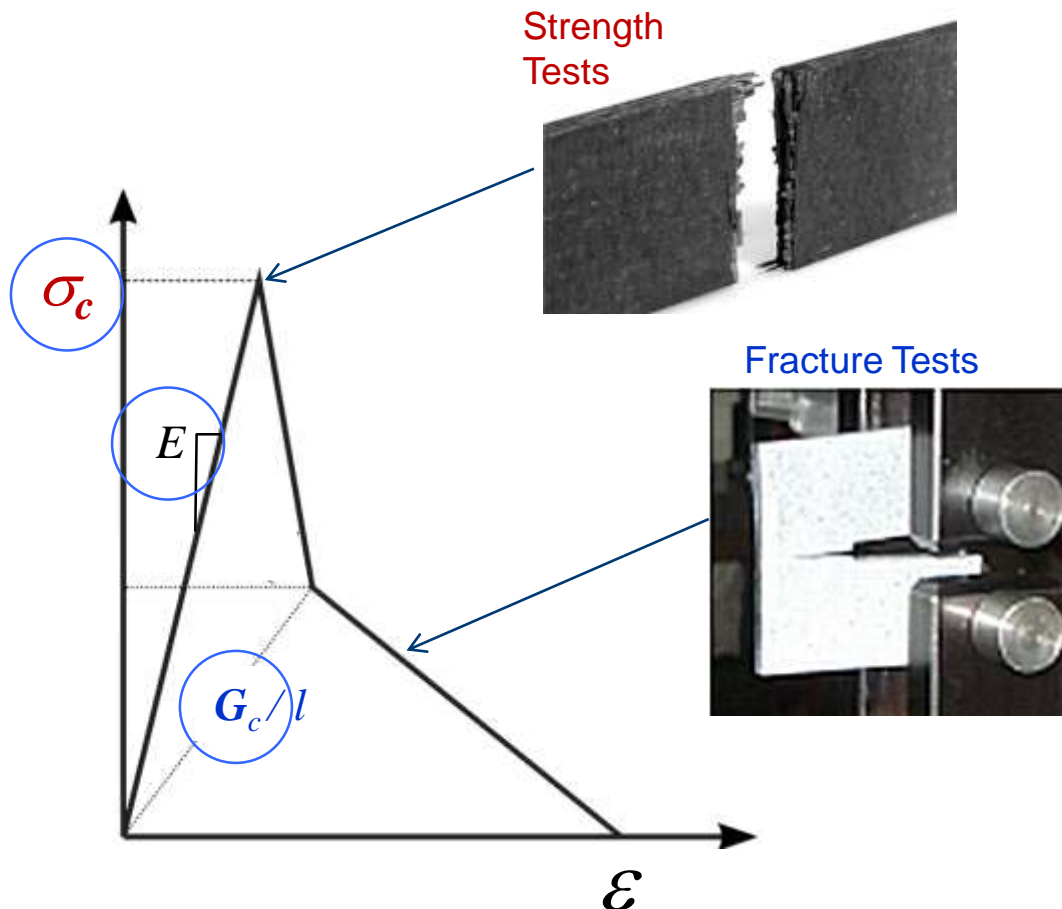
Crack Length and Process Zone





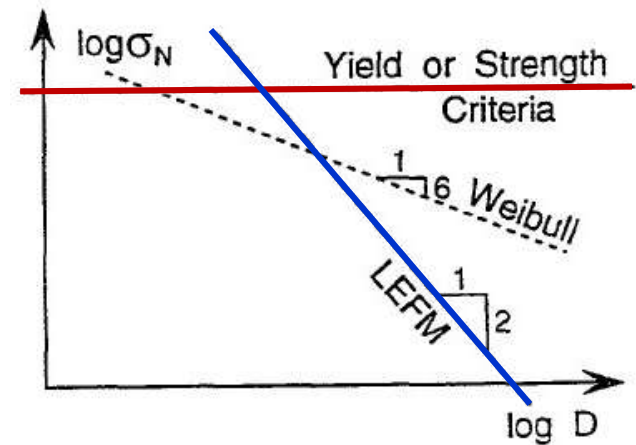
Damage Evolution Laws:

Each damage mode has its own softening response



Two material properties:

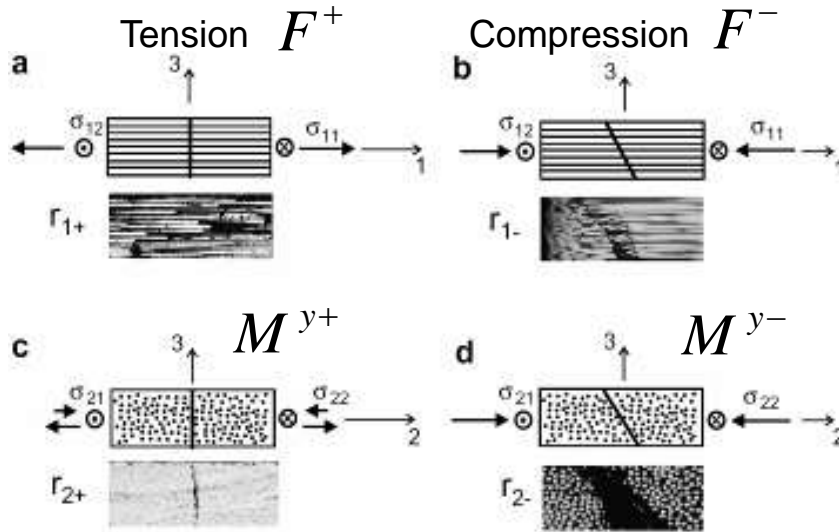
- σ_c Strength
- G_c Fracture toughness



Material length scale

$$l_c \approx \gamma \frac{E G_c}{\sigma_c^2}$$

Damage Modes:



LaRC04 Criteria

- In-situ matrix strength prediction
- Advanced fiber kinking criterion
- Prediction of angle of fracture (compression)
- Criteria used as activation functions within framework of continuum damage mechanics (CDM)

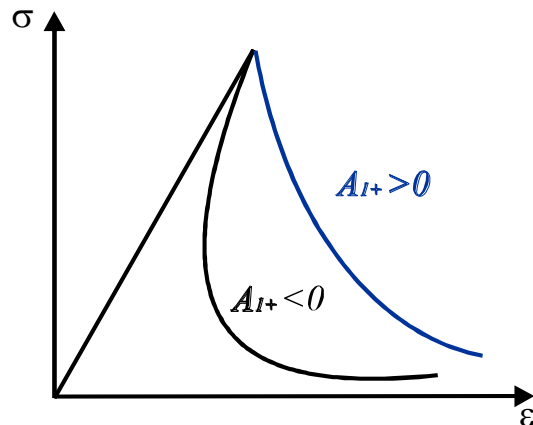
$$d_i = 1 - \frac{1}{f_i} \exp(A_i(1 - f_i))$$

f_i : LaRC04 failure criteria as activation functions

$$i = F^+; F^-; M^{y+}; M^{y-}; M^s$$

Damage Evolution:

Thermodynamically-consistent material degradation takes into account energy release rate and element size for each mode



Bazant Crack Band Theory:

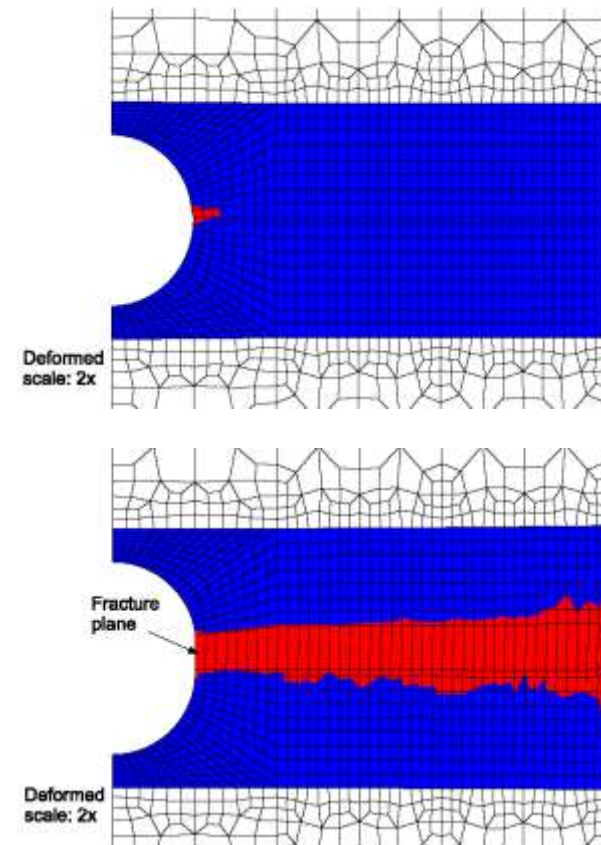
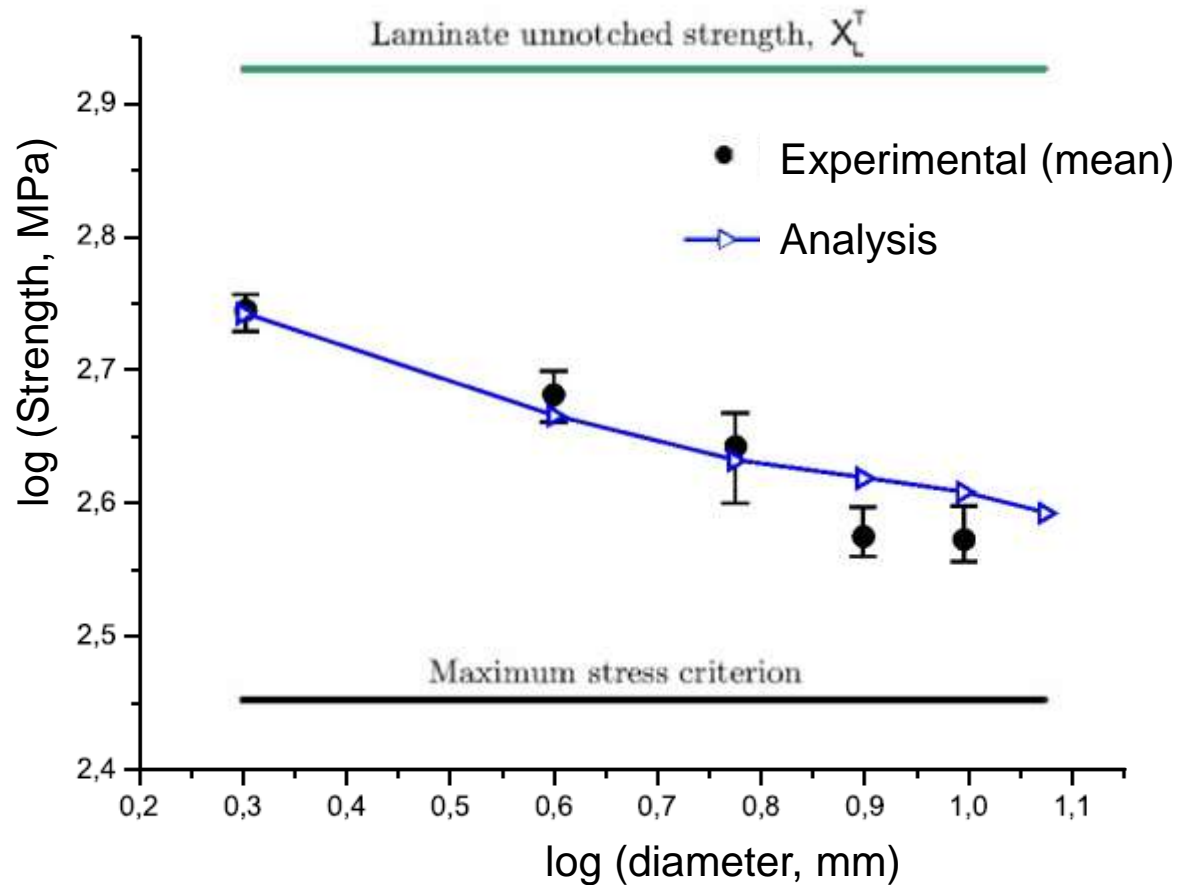
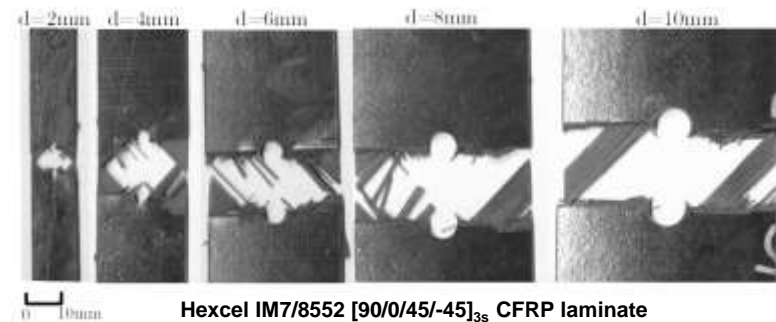
$$A_i = \frac{2l^* X_i^2}{2E_i G_i - l^* X_i^2}$$

Critical (maximum) finite element size:

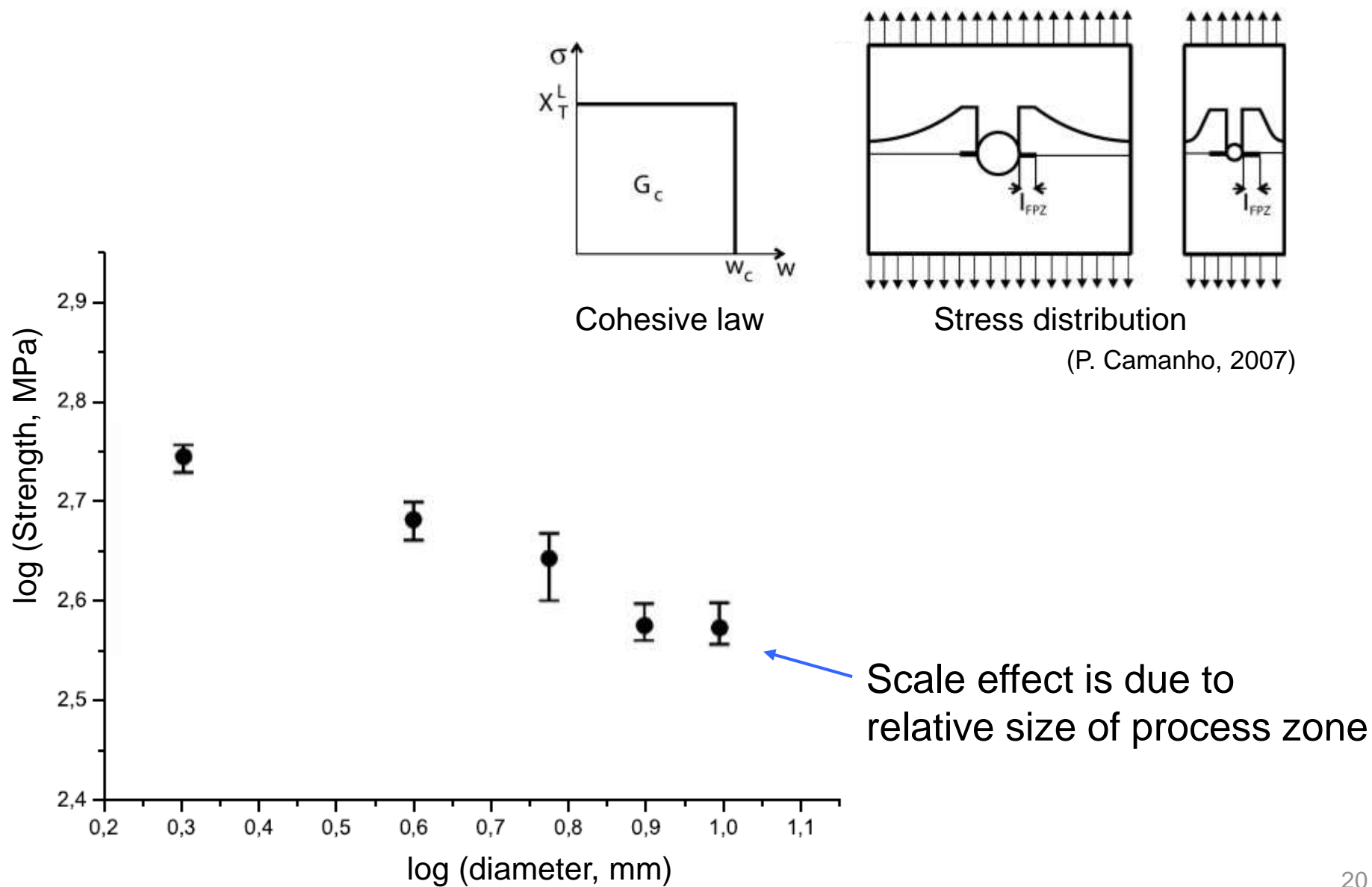
$$l^* \leq \frac{2E_i G_i}{X_i^2}$$

Prediction of size effects in notched composites

- Stress-based criteria predict no size effect
- CDM damage model predicts scale effects w/out calibration
(P. Camanho, 2007)



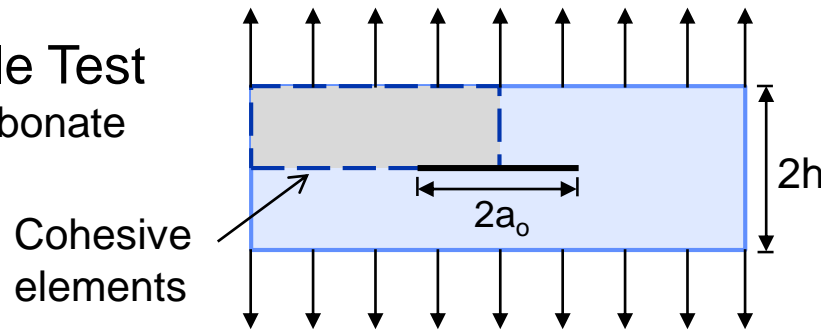
Process Zone and Scale Effect in Open Hole Tension



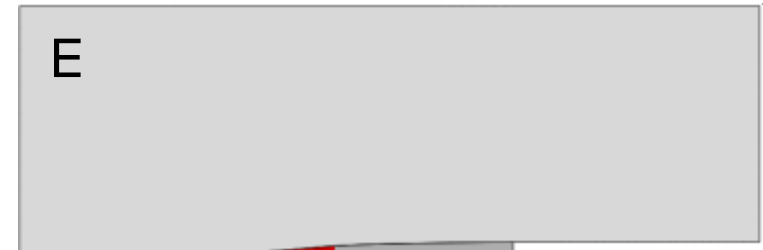
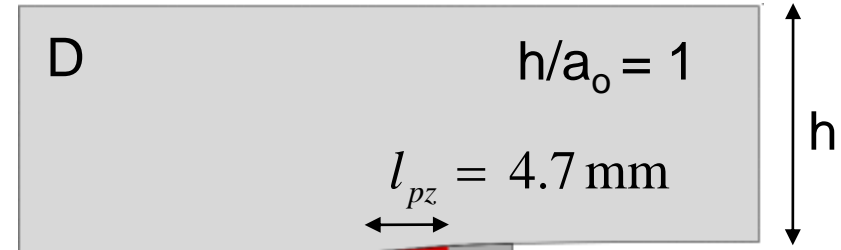
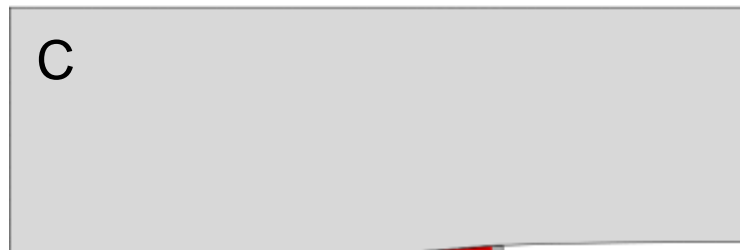
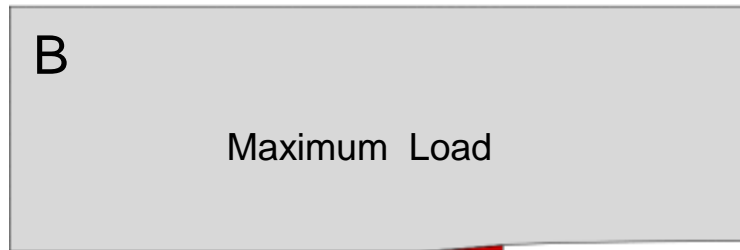
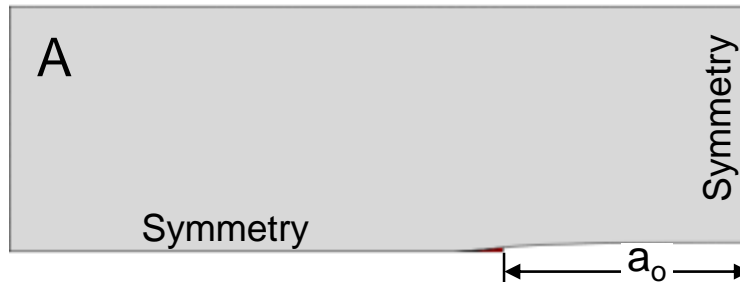
Length of the Process Zone (Elastic Bulk Material)



Short Tensile Test
Lexan Polycarbonate

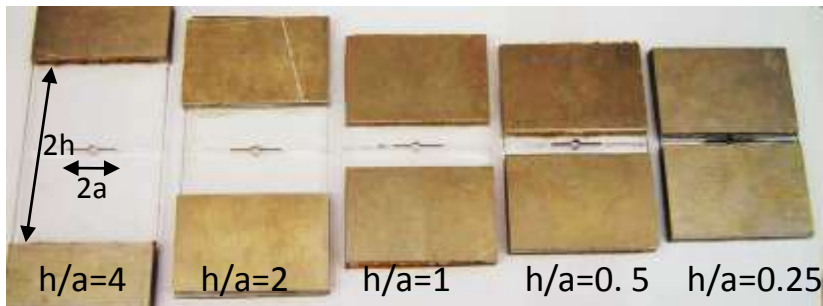


$$l_c \approx 0.6 \frac{E G_c}{\sigma_c^2} = 3.4 \text{ mm}$$

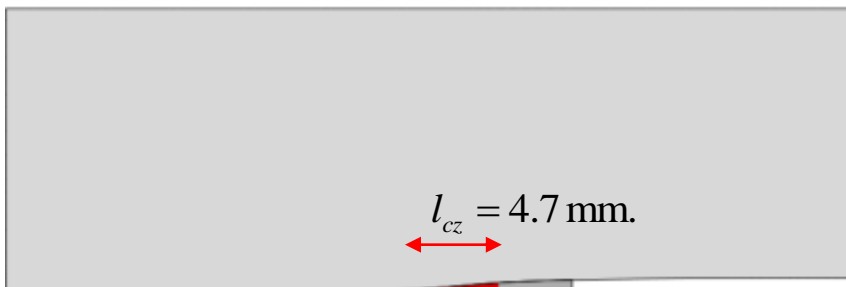


- The use of cohesive laws to predict the fracture in complex stress fields is explored
- The bulk material is modeled as either elastic or elastic-plastic

Lexan Plexiglass tensile specimens (CT Sun)

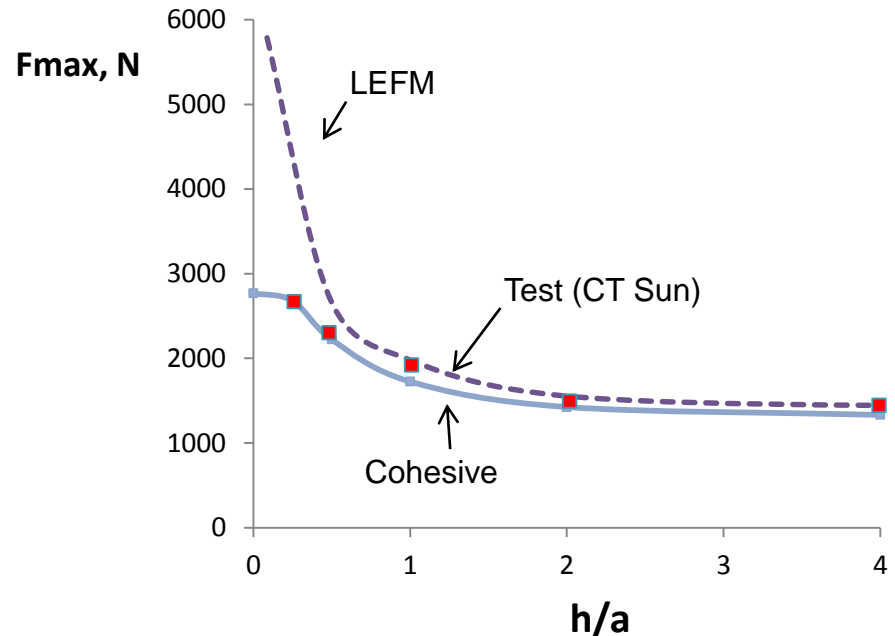


$h/a=1$ (short process zone)



Observations:

- LEFM overpredicts tests for $h/a < 1$



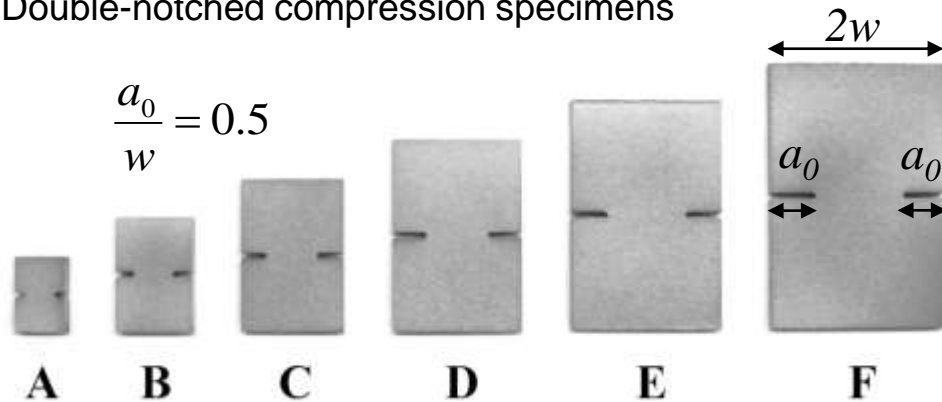
$h/a = 0.25$ (long process zone)



Study of size effect: measuring the R-curve



Double-notched compression specimens



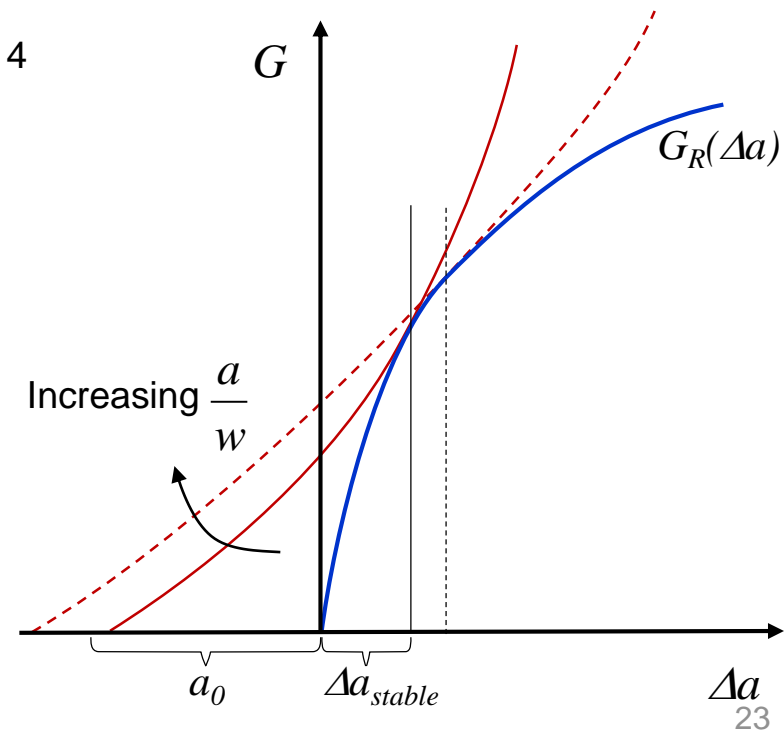
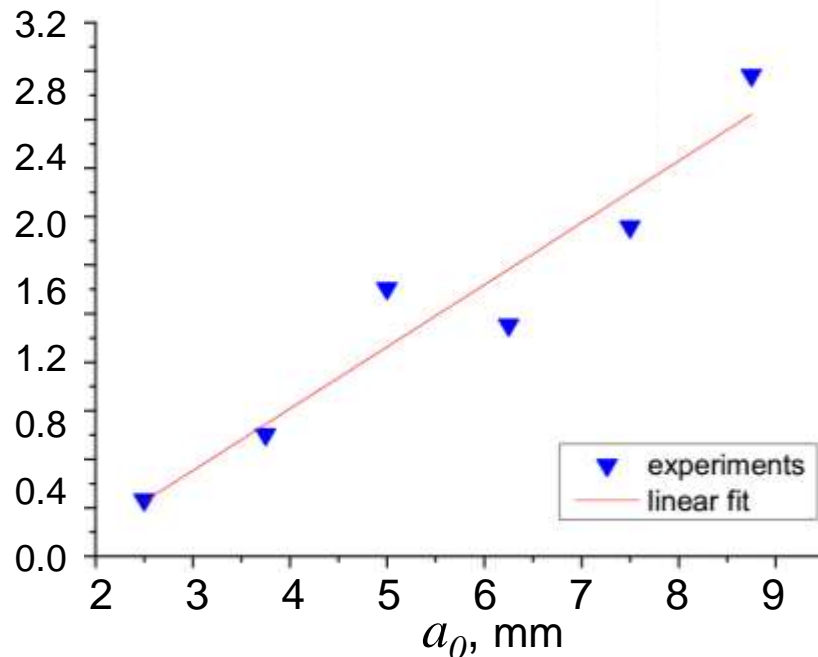
By FEM analysis From test

$$G = \underbrace{\phi\left(\frac{a}{w}\right)}_{\text{By FEM analysis}} \underbrace{\frac{\sigma_u^2 a}{E^{eff}}}_{\text{From test}}$$

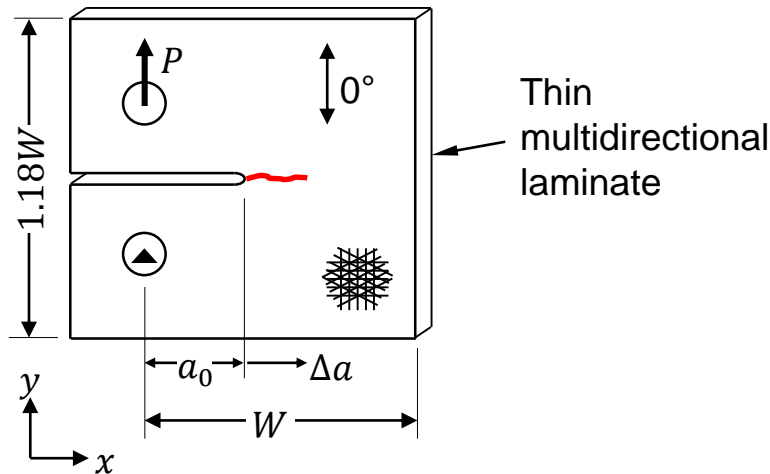
(Similar to $G = \frac{\pi \sigma^2 a}{E}$)

σ_u^{-2} , $\text{MPa}^{-2} \cdot 10^{-5}$

Catalanotti, et al., *Comp A*, 2014

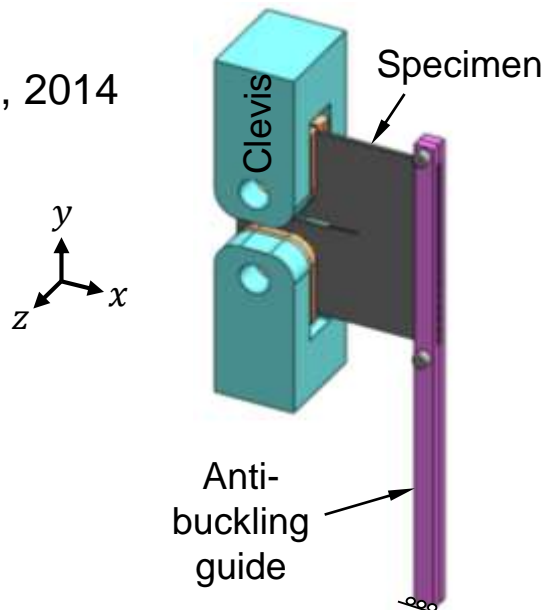


Compact Tension (CT) Specimen



Experimental setup

Bergan, 2014



Characterization Procedure:

1. Measure R-curve from CT test

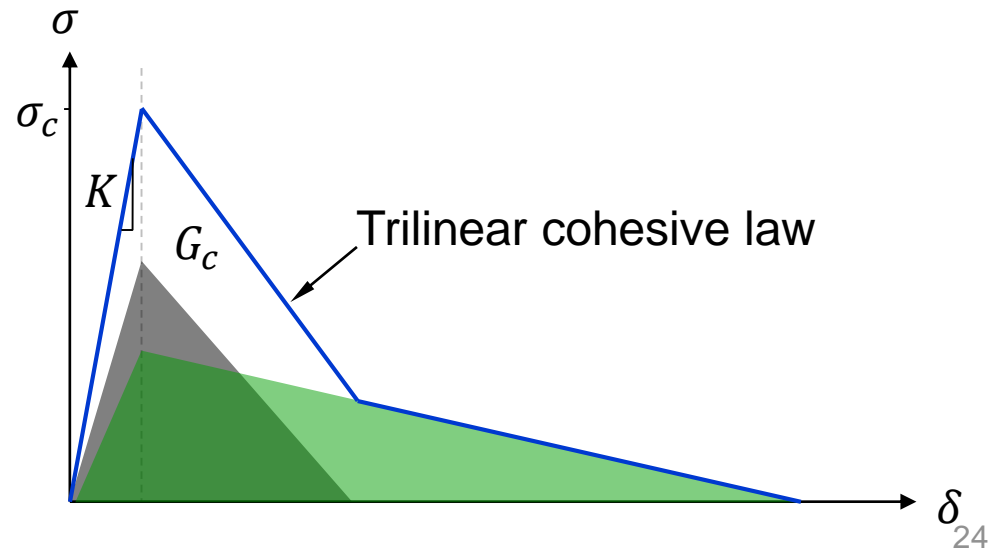
$$G_R = \frac{P^2}{2t} \frac{\partial C}{\partial a}$$

2. Assuming a trilinear cohesive law, fit analytical R-curve to the measured R-curve

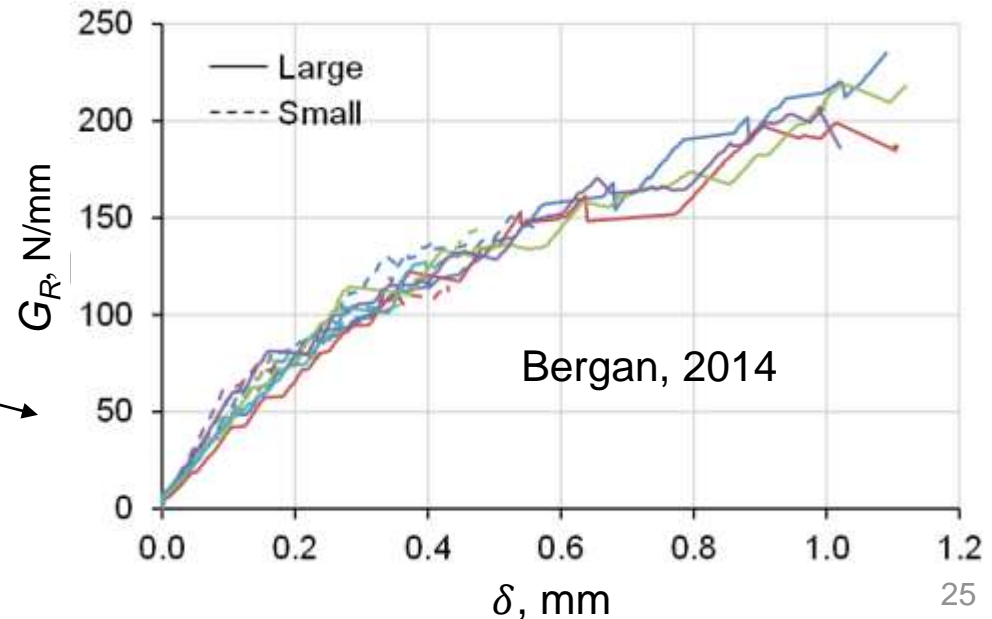
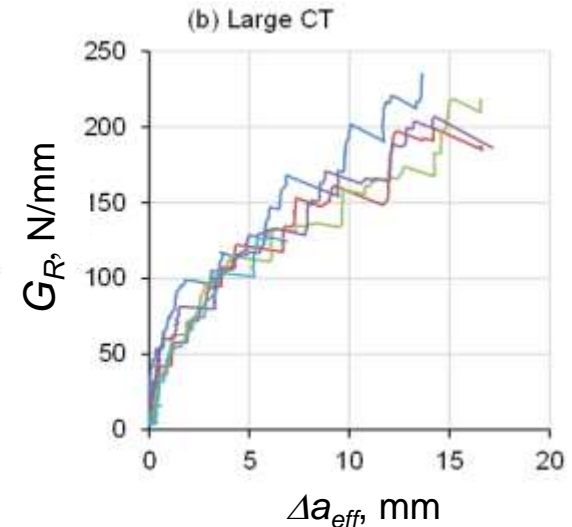
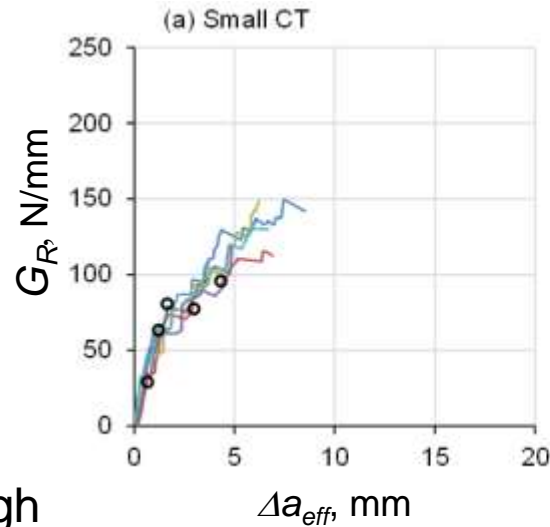
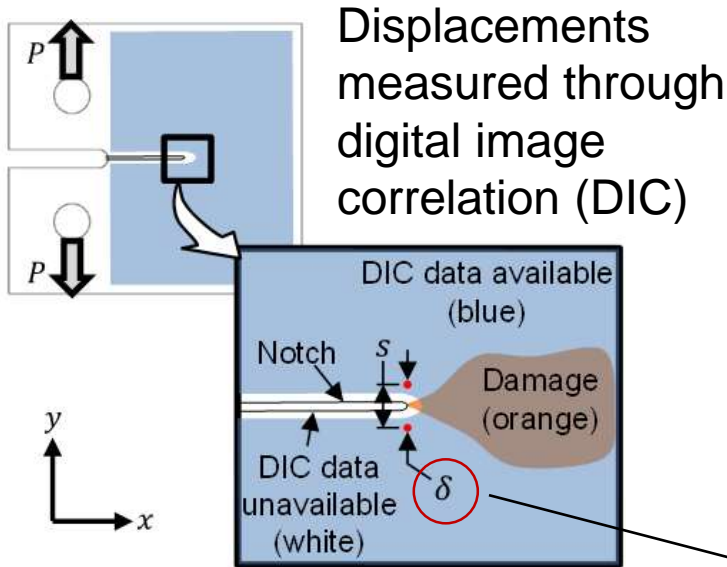
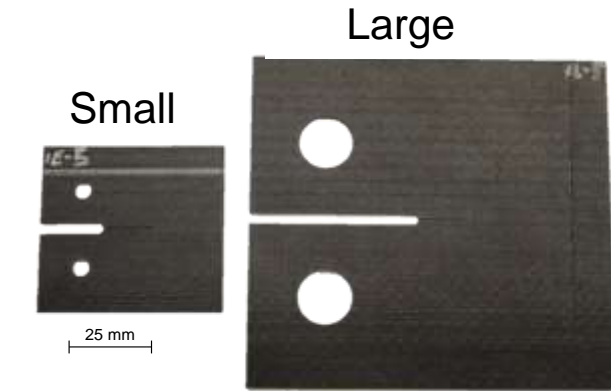
$$\eta = \sum_i^{n_s} |J_{\text{fit}}^i - G_R^i|$$

3. Obtain the cohesive law by differentiating the analytical R-curve

$$\sigma(\delta) = \frac{\partial J_{\text{fit}}}{\partial \delta}$$

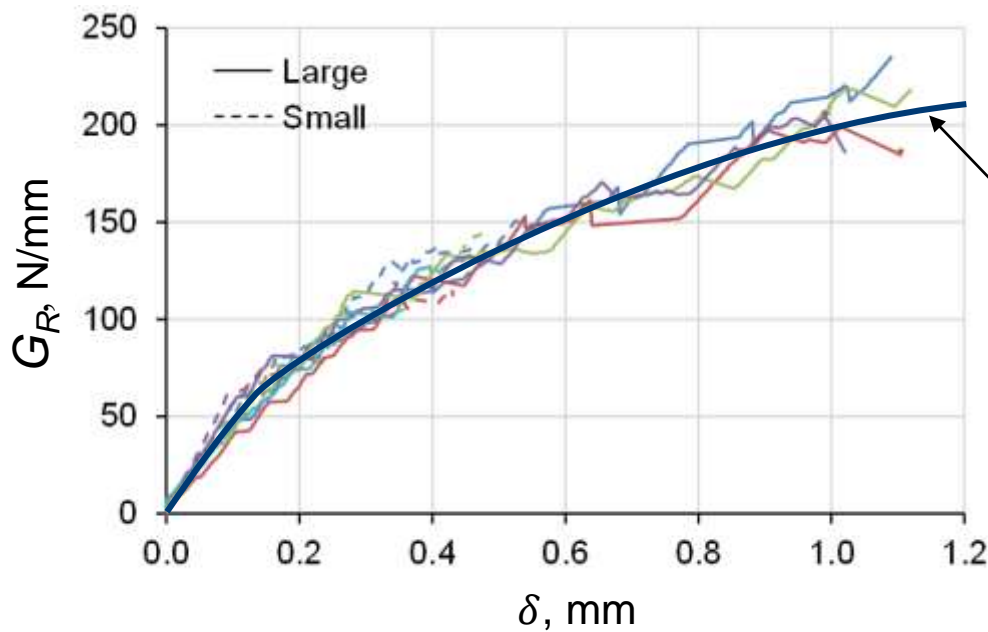


Size-Dependence of R-Curve



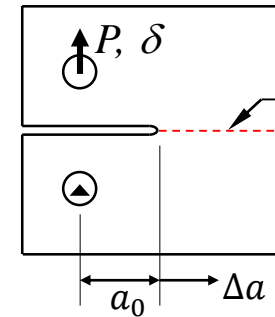
Plotting the R-curve as a function of the notch displacement removes the size-dependency

R-Curve Effect in Fiber Fracture

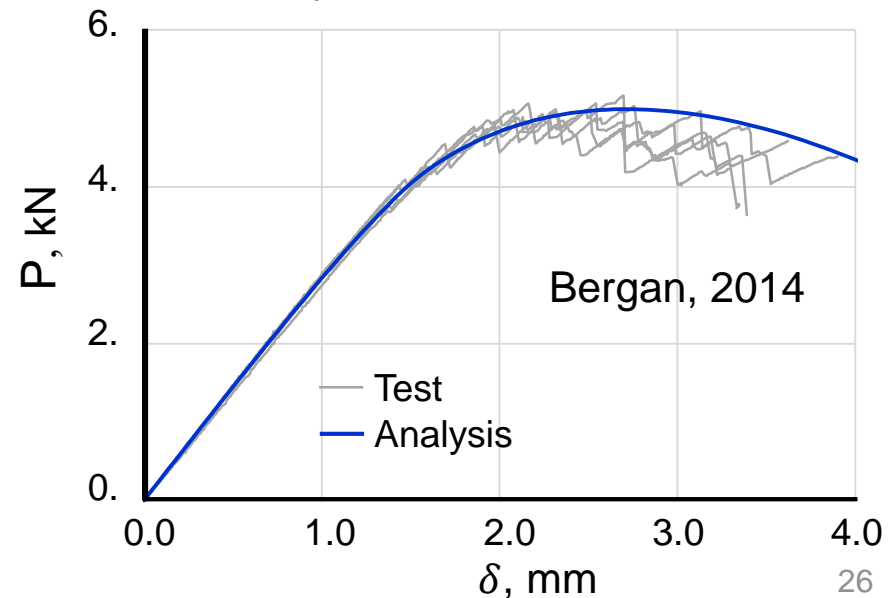
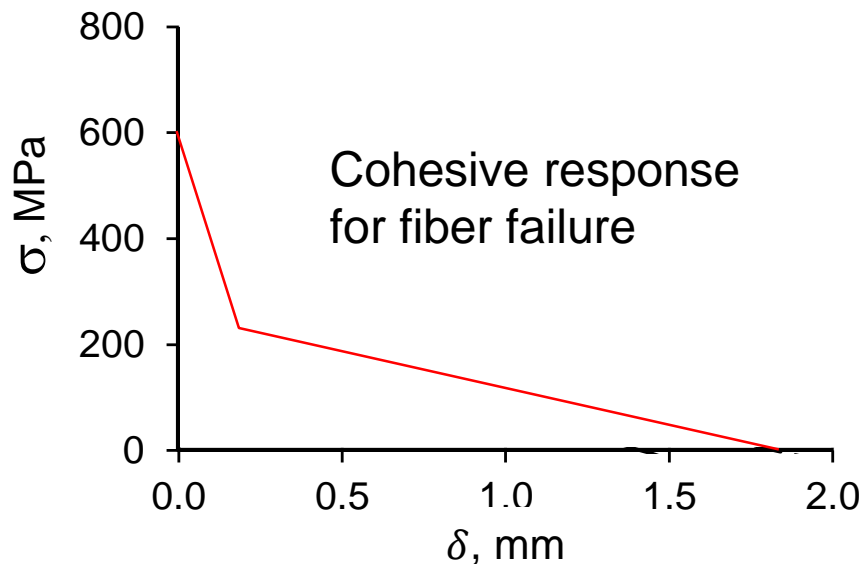


$$J_R = \int_0^{\delta_c} \sigma(\delta) d\delta$$

Curve fit assuming bilinear $\sigma(\delta)$

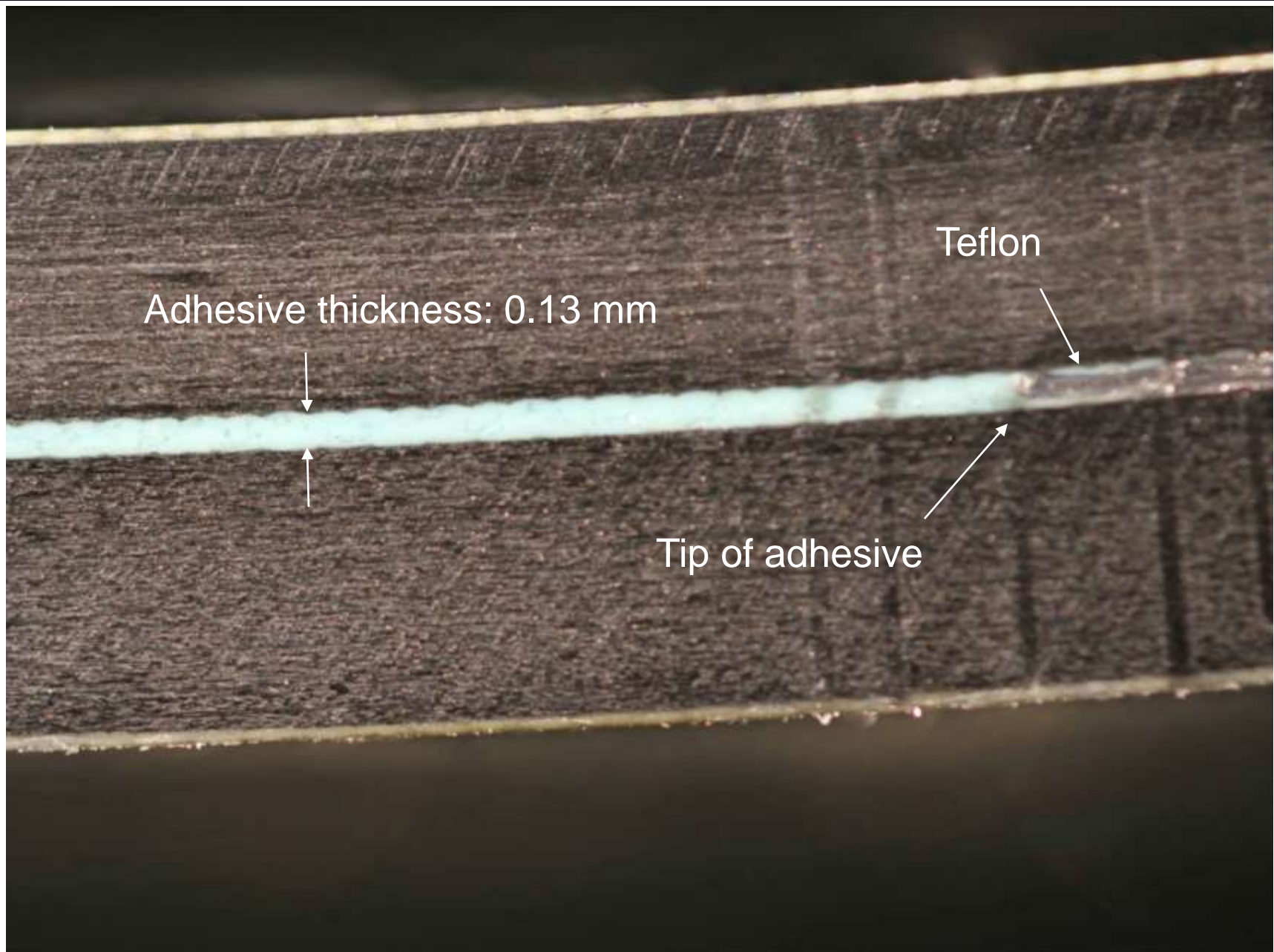


Cohesive elements w/ characterized cohesive law

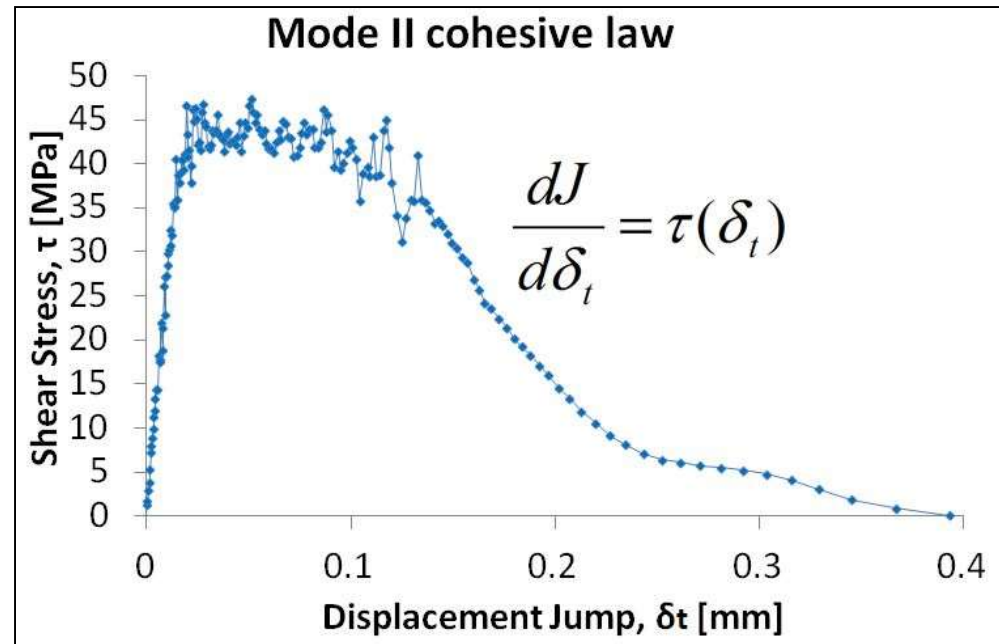
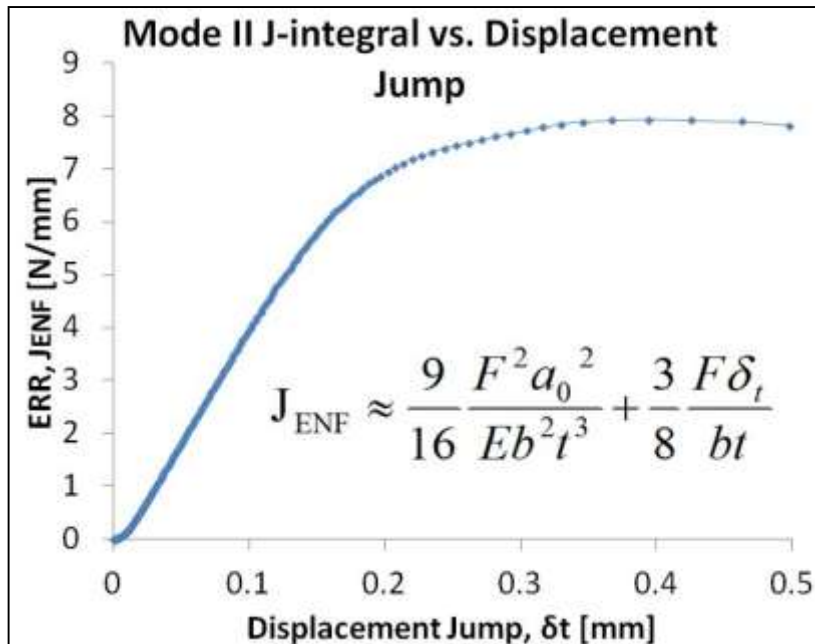
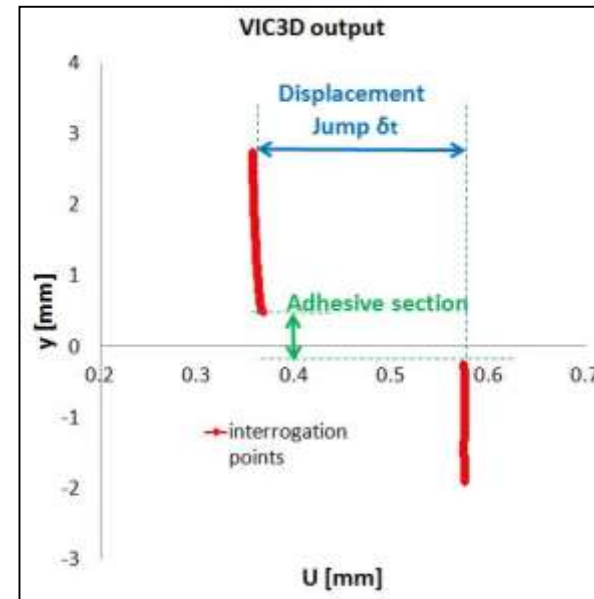
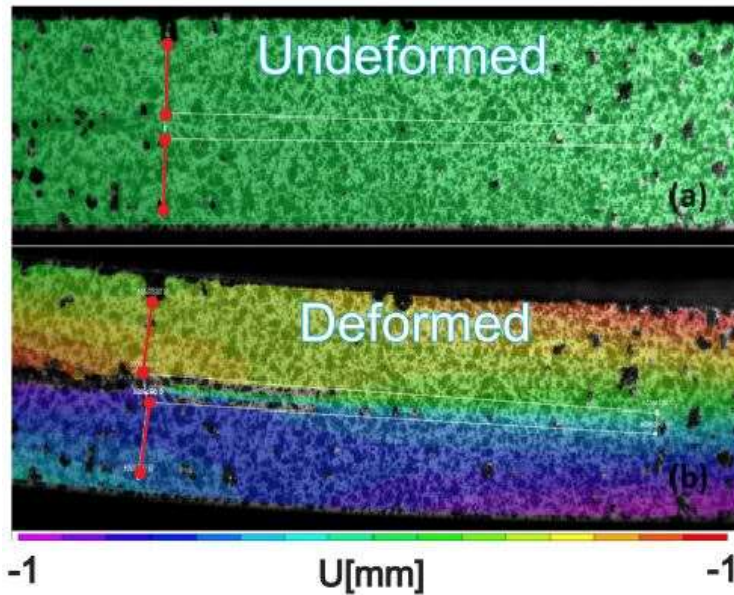


Bergan, 2014

Mode II-Dominated Adhesive Fracture



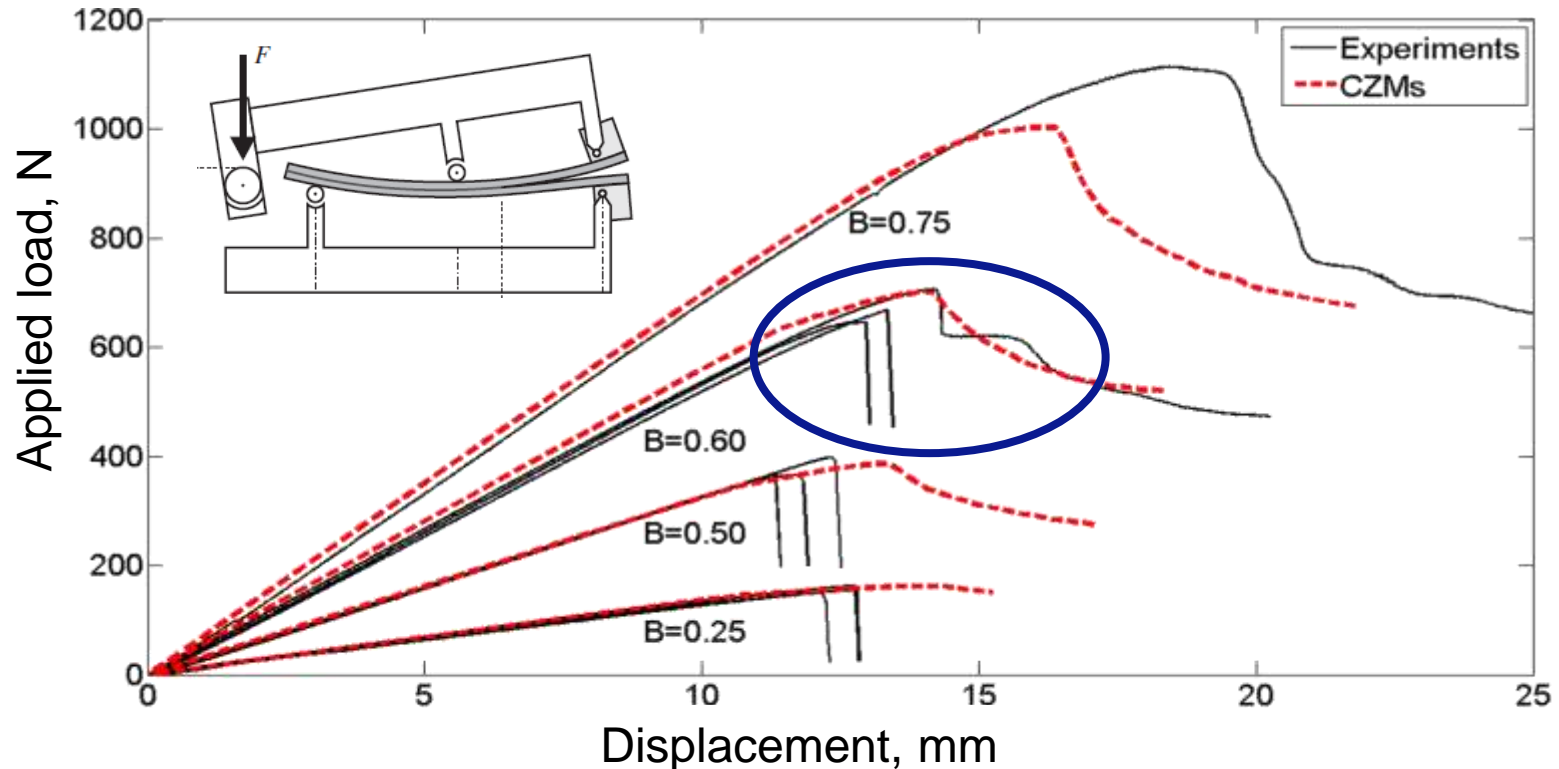
ENF J-Integral from DIC



MMB Test - Analysis Results



Mixed mode bending (MMB) test fixture

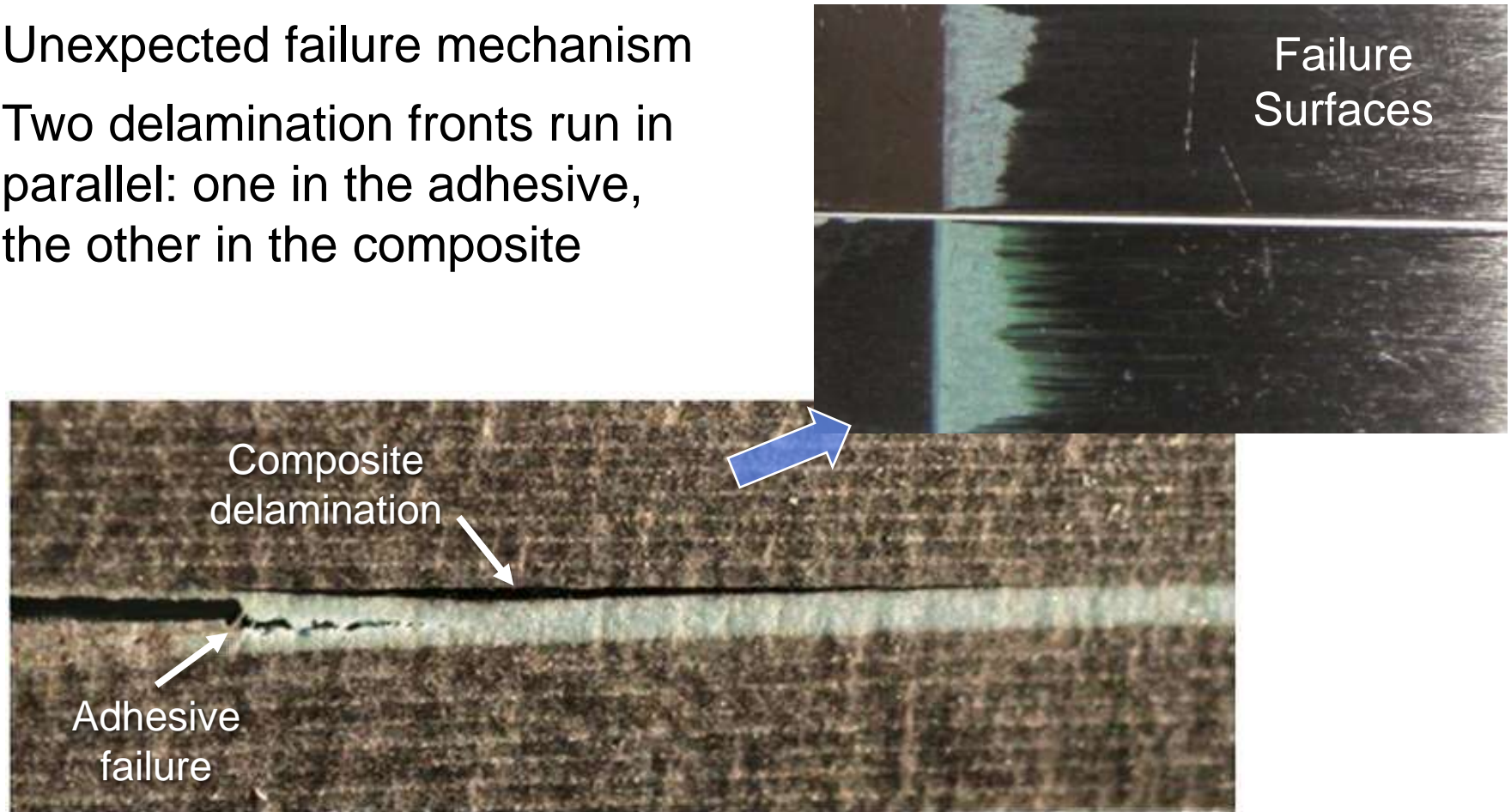


Nominally identical bonded MMB specimens sometimes fail in quasi-static mode and others dynamically. Why?

Double Delamination in MMB Tests



- Unexpected failure mechanism
- Two delamination fronts run in parallel: one in the adhesive, the other in the composite



- When the fiber bridge breaks, the crack grows unstably in the composite causing the drop in the load-displacement curve

Modeling the Double Delamination

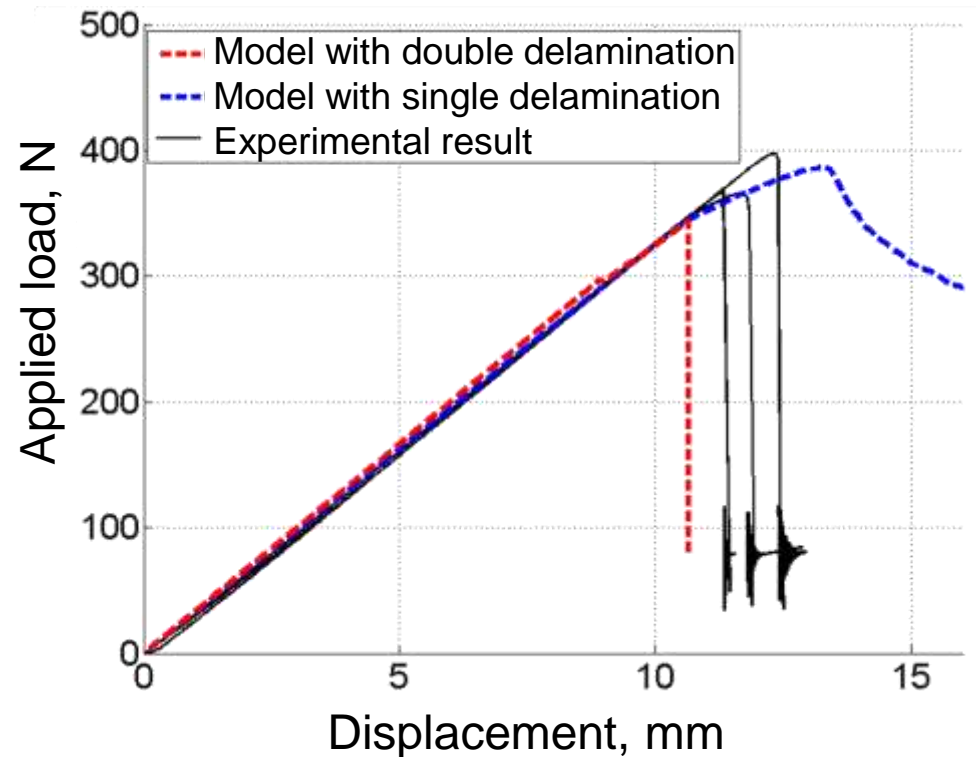
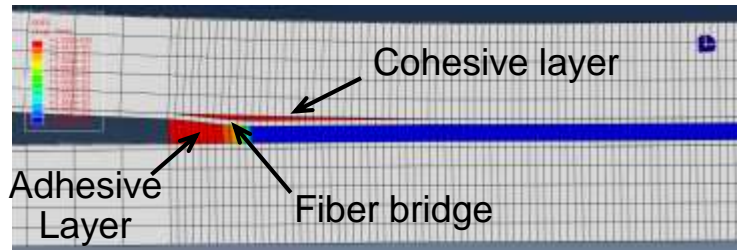


- A model was developed to evaluate the observed double delamination phenomenon
- The model contains two additional cohesive layers within the composite arms

MMB test specimen



Model of MMB specimen with double delamination



- This failure mechanism is often observed in bonded joints

Why Micromechanics?

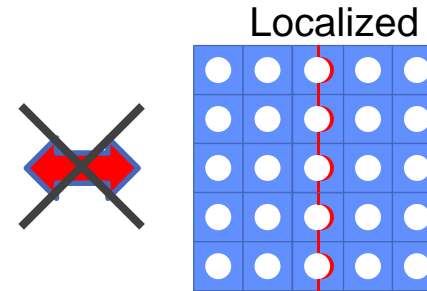
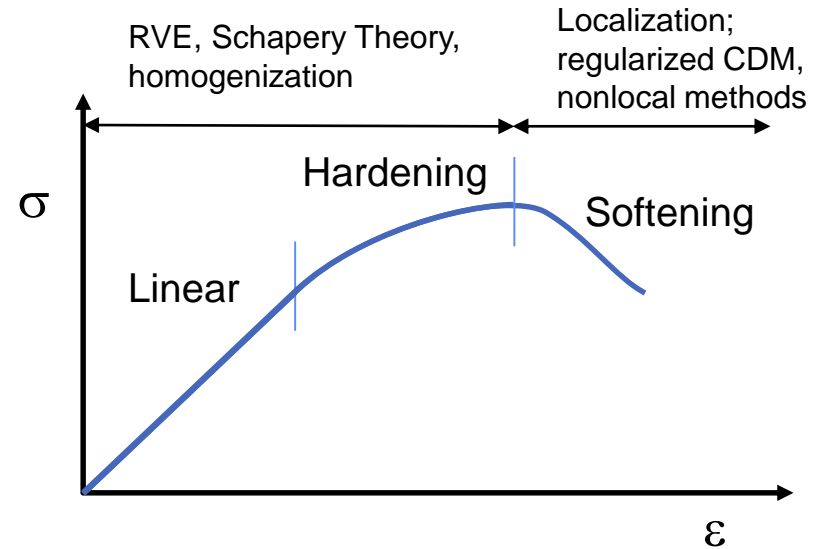
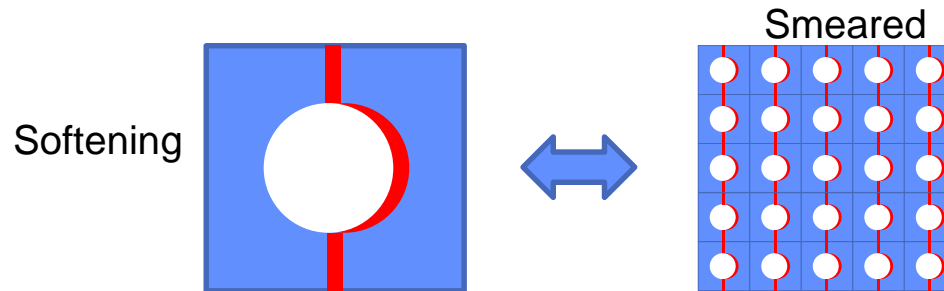
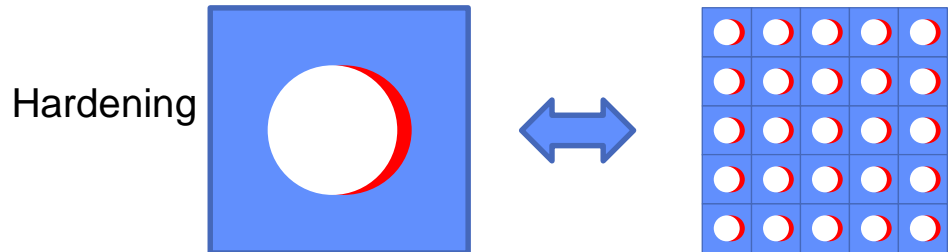
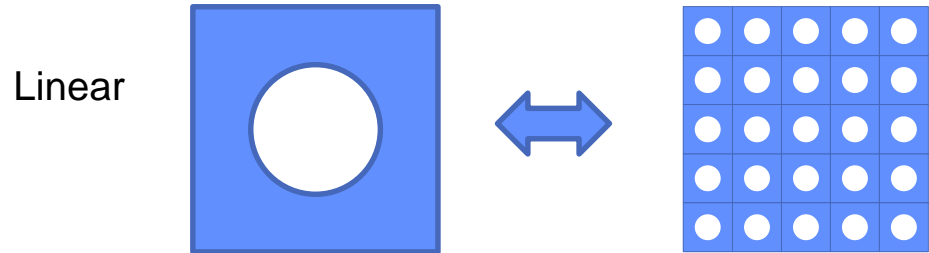
Assumption:

*“Micromechanics has **more built-in physics** because it is closer to the scale at which fracture occurs”*

Why NOT Micromechanics? (Representative Volume Element [RVE])

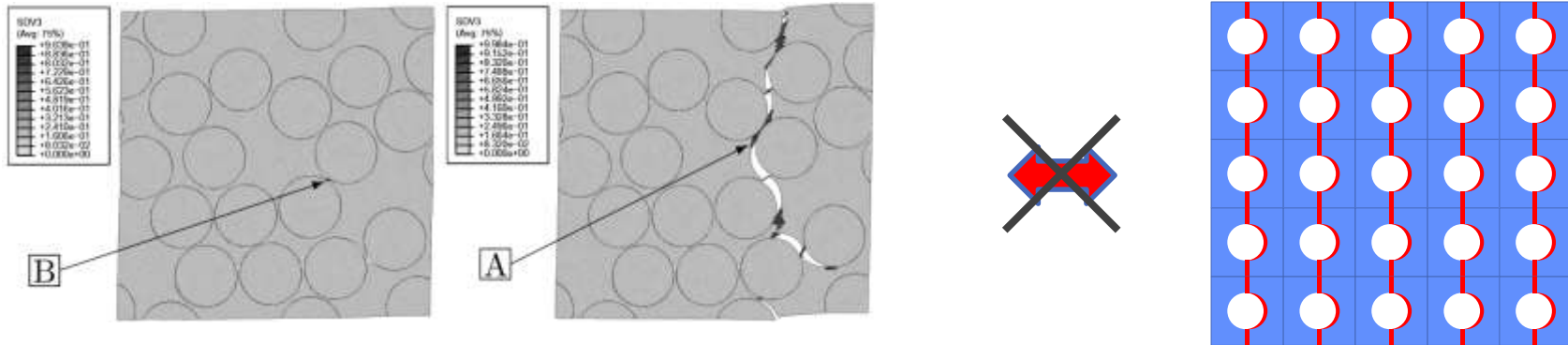
- Problem of localization
- Randomness of unit cell configurations
- Lengthscales missing
- Characterization of material properties, especially the interface
- Computational expense

RVE: 1) Problem of Localization



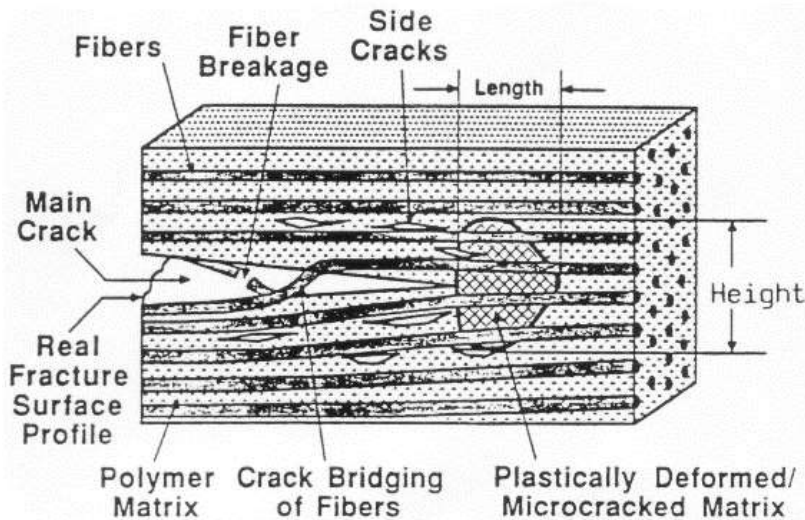
Scale of RVE
cannot be
eliminated

RVE: 2) Randomness of Unit Cell Configurations



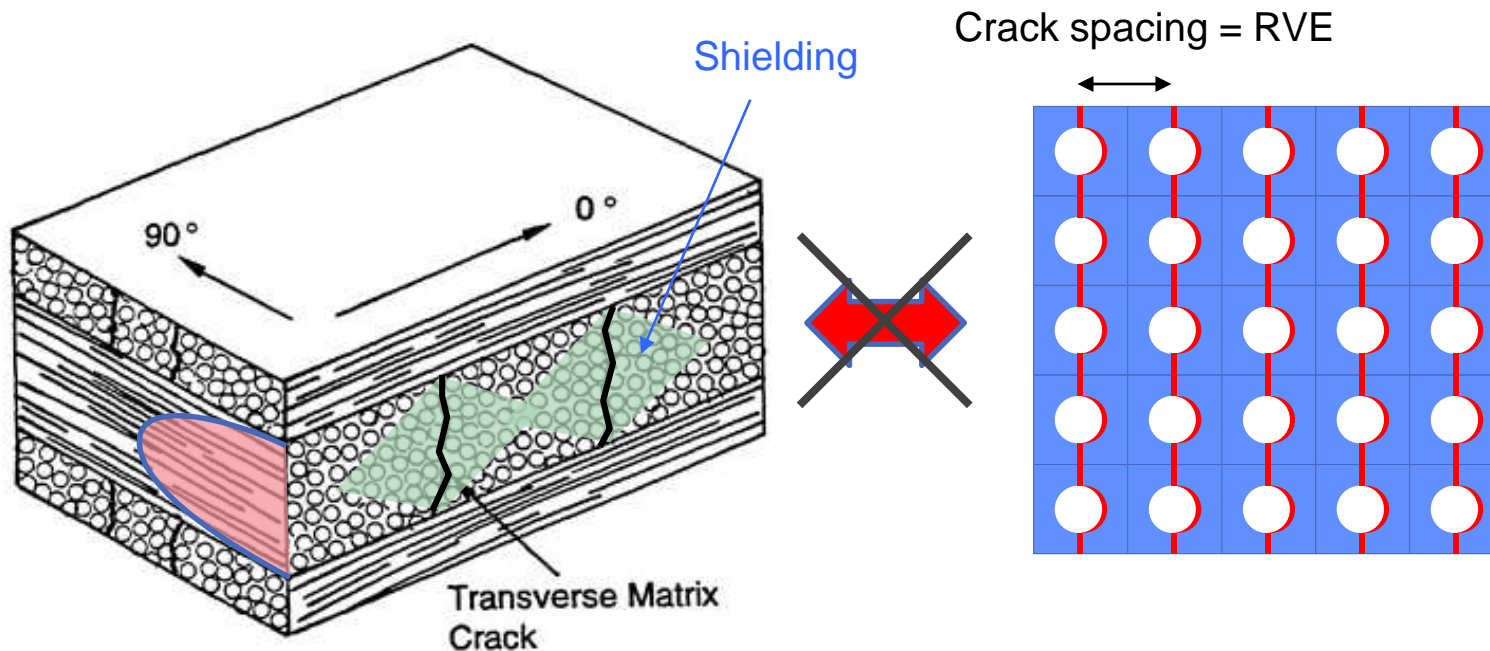
Melro et al. *IJSS*, 2013.

Fracture is a combination of interacting discrete and diffuse damage mechanisms



Bloodworth, V., PhD Dissertation, Imperial College, UK, 2008.

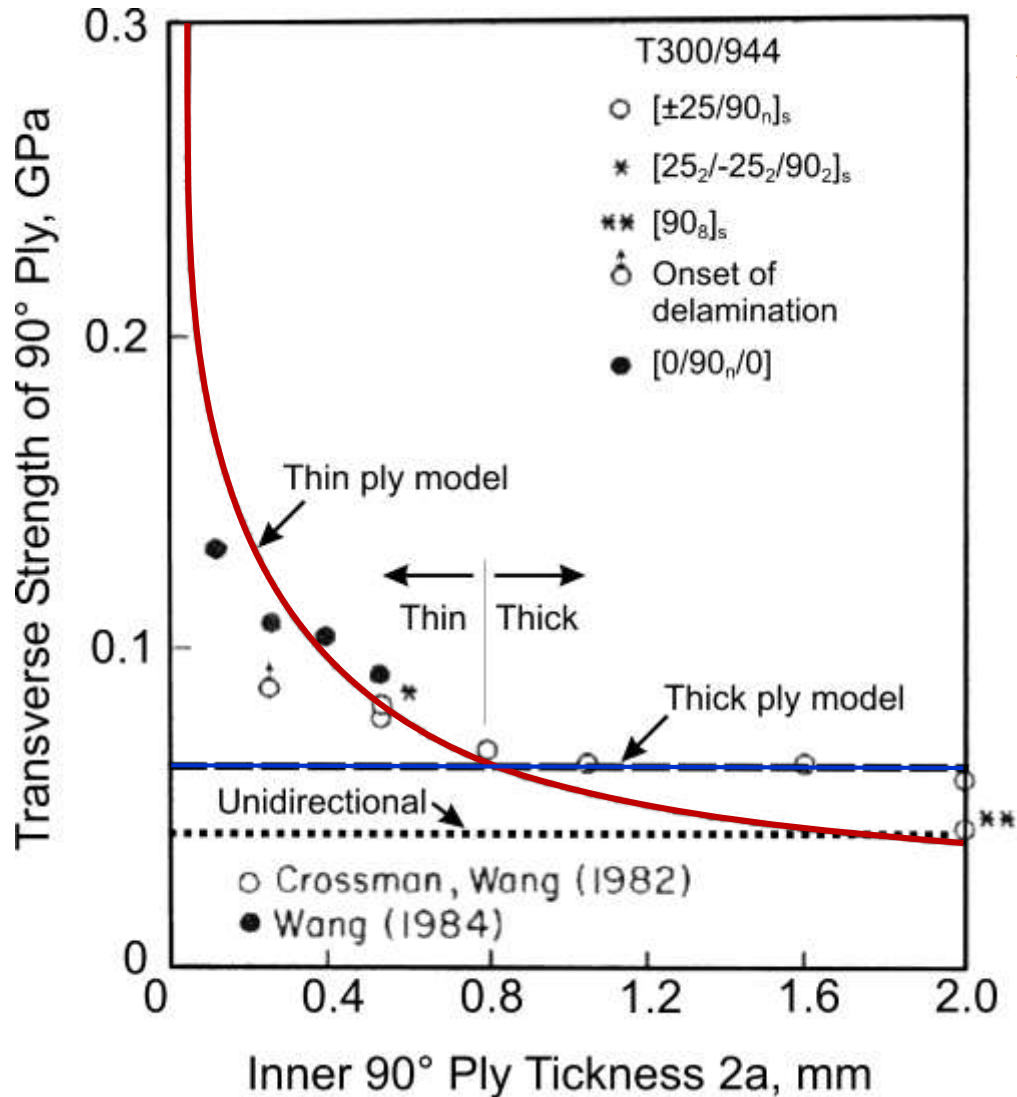
RVE: 3) Issue of Length Scales



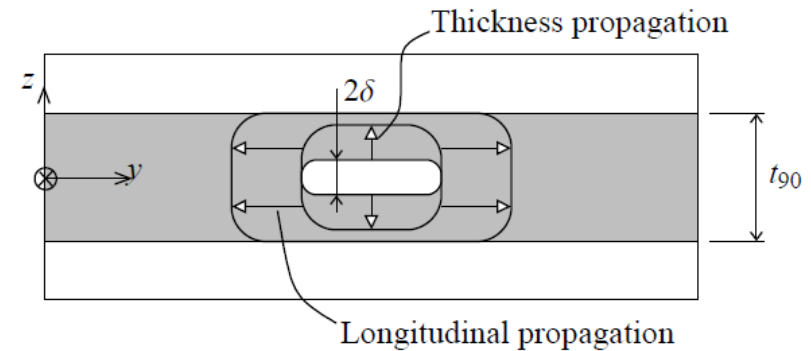
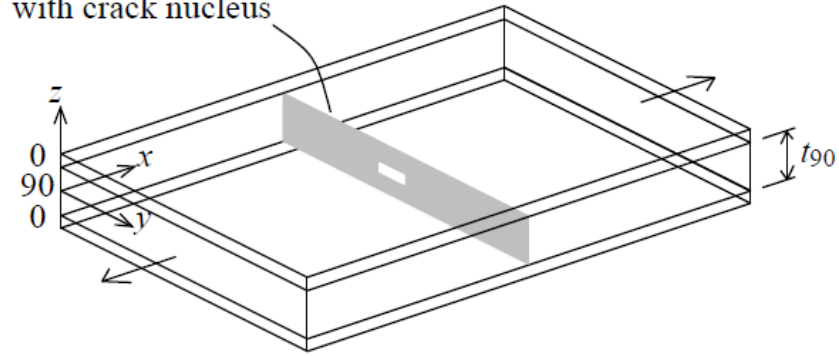
RVE may not account for:

- Ply thickness
- Longitudinal crack length
- Crack spacing

Matrix Cracking – In Situ Effect



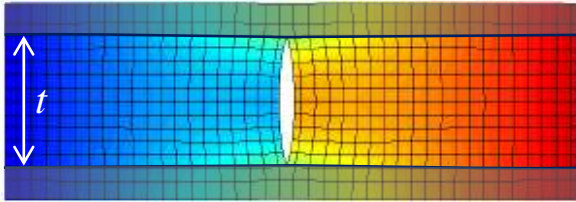
Potential crack plane,
with crack nucleus



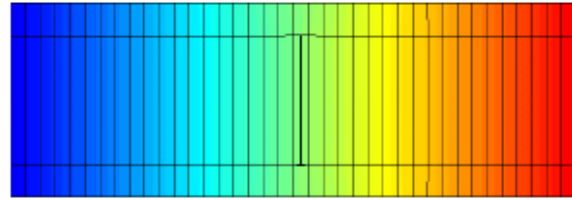
Transverse Matrix Cracks w/ One Element Per Ply



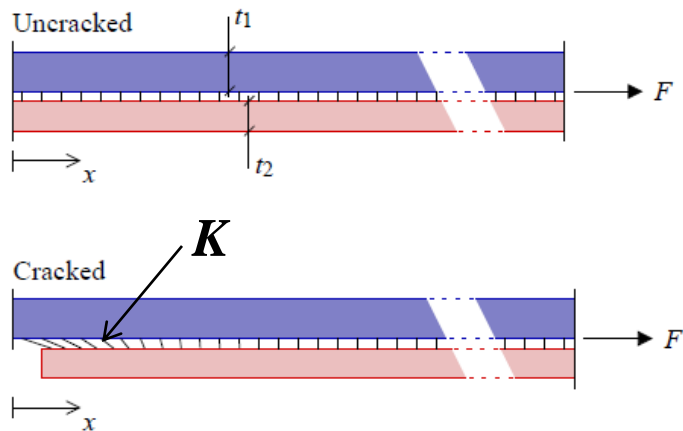
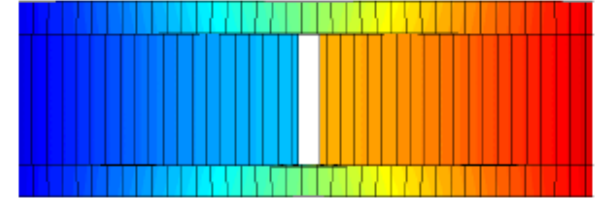
Multi-element model:
correct crack evolution



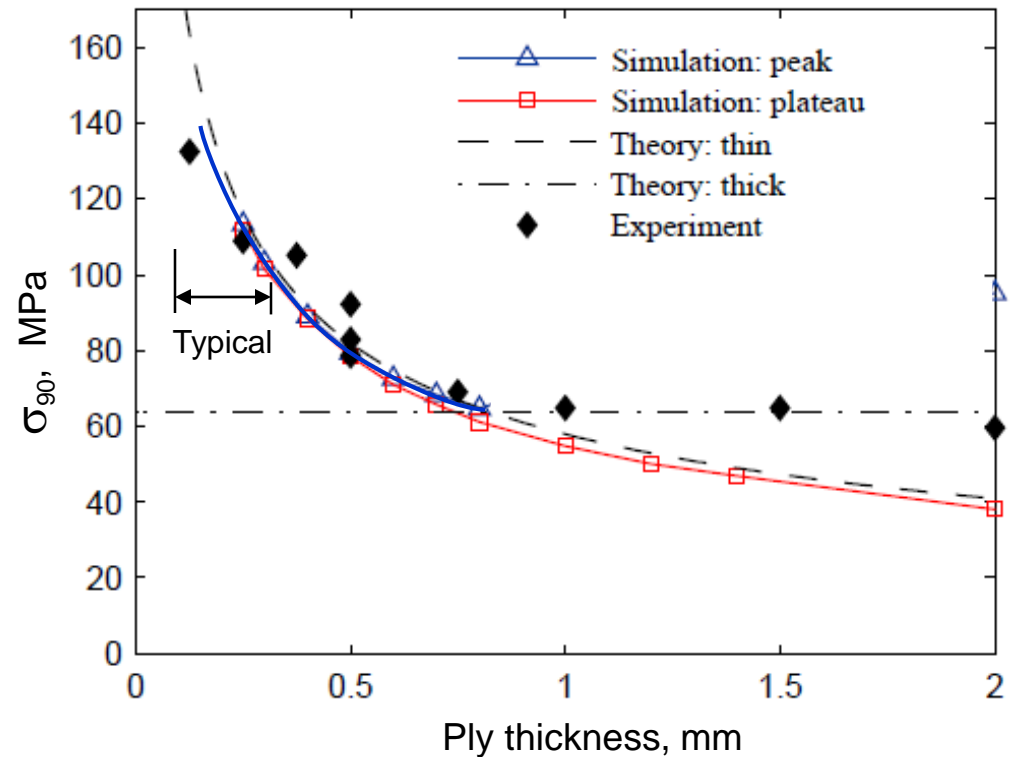
Conventional single-element:
no opening w/out delam.



Modified single-element:
correct Energy Release Rate



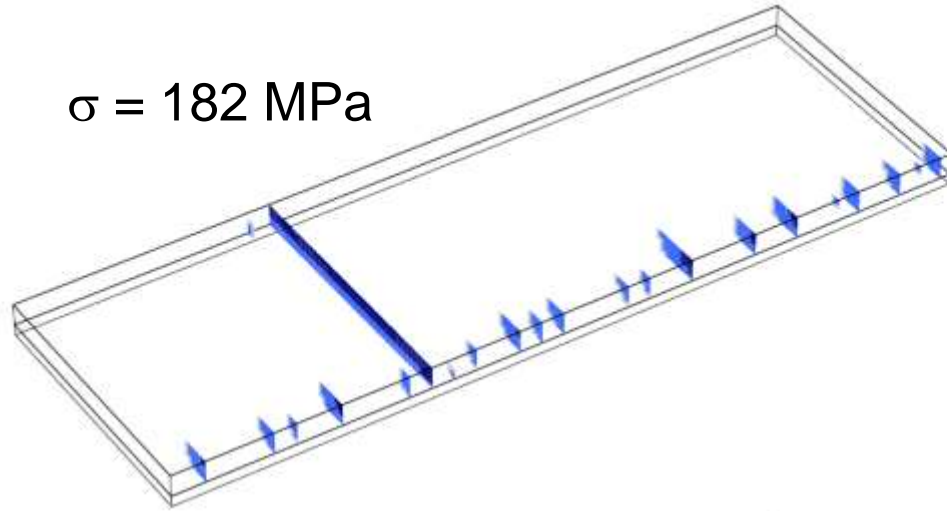
$$K \approx \frac{4E_2}{\pi^2 t}$$



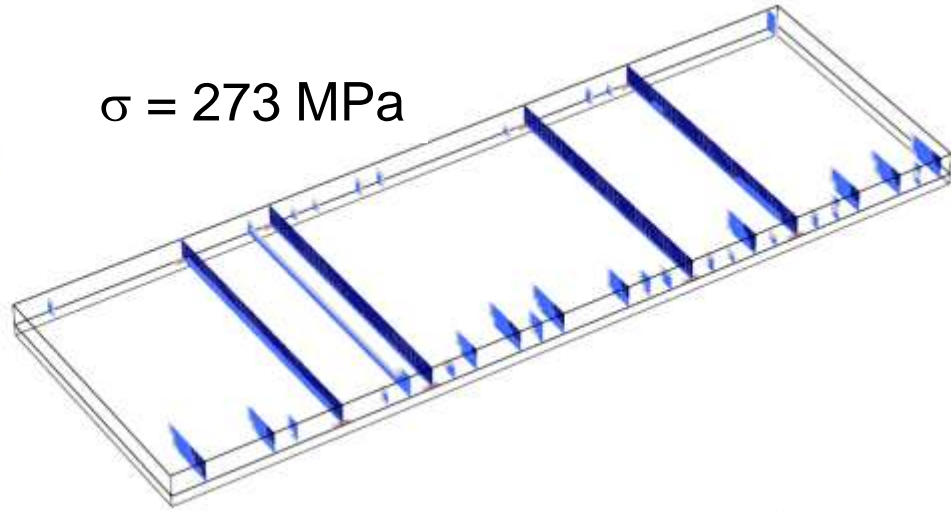
Crack Initiation, Densification, and Saturation



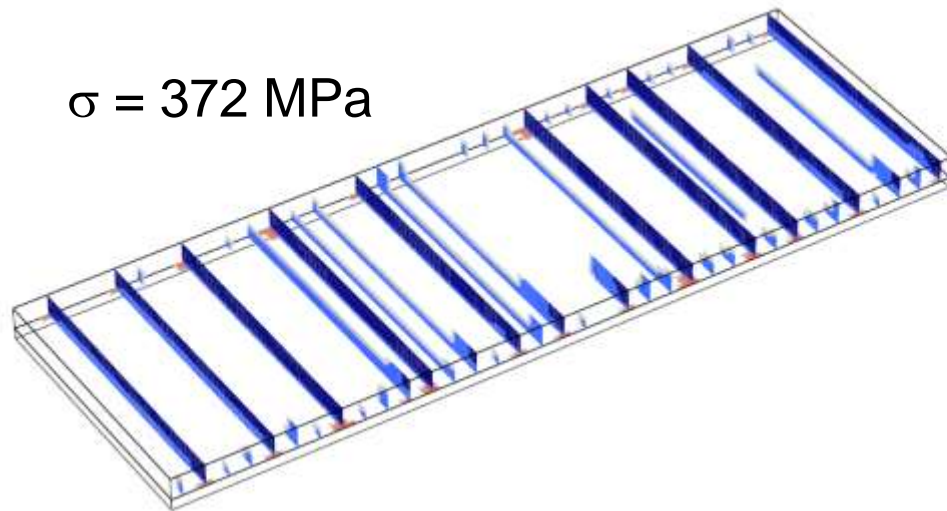
$\sigma = 182 \text{ MPa}$



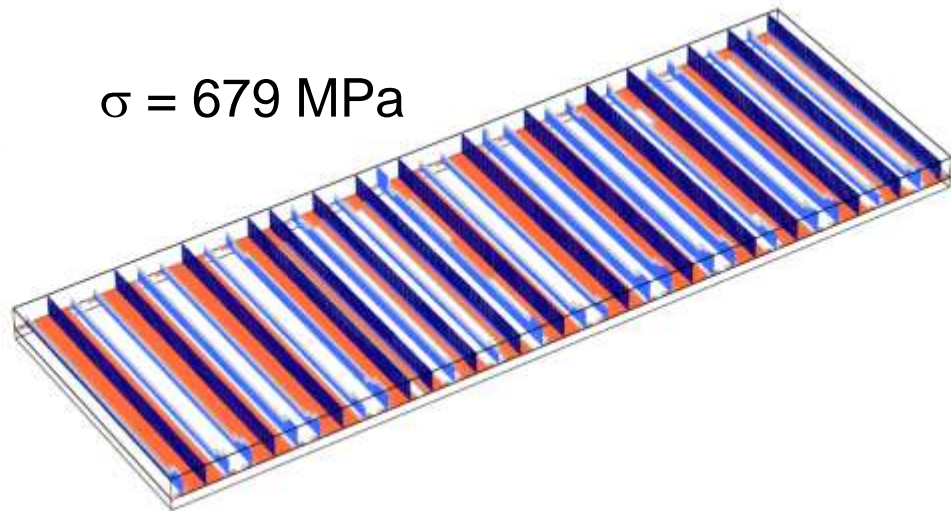
$\sigma = 273 \text{ MPa}$






$\sigma = 372 \text{ MPa}$

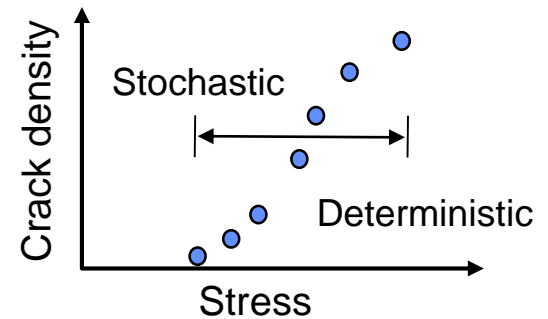


$\sigma = 679 \text{ MPa}$

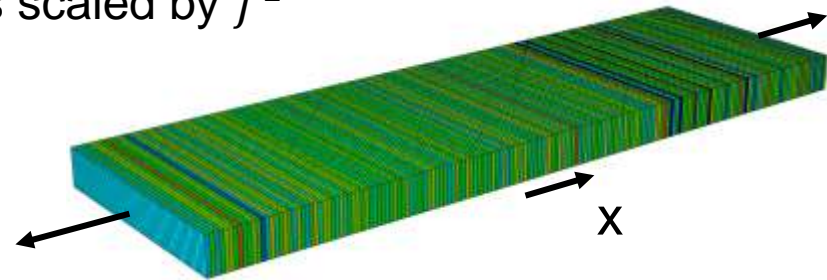


-  Cohesive zone
-  Traction-free cohesive zone
-  Delamination

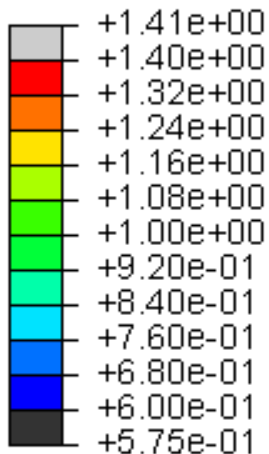
Initial crack density in a uniformly stressed laminate is strictly a function of material inhomogeneity



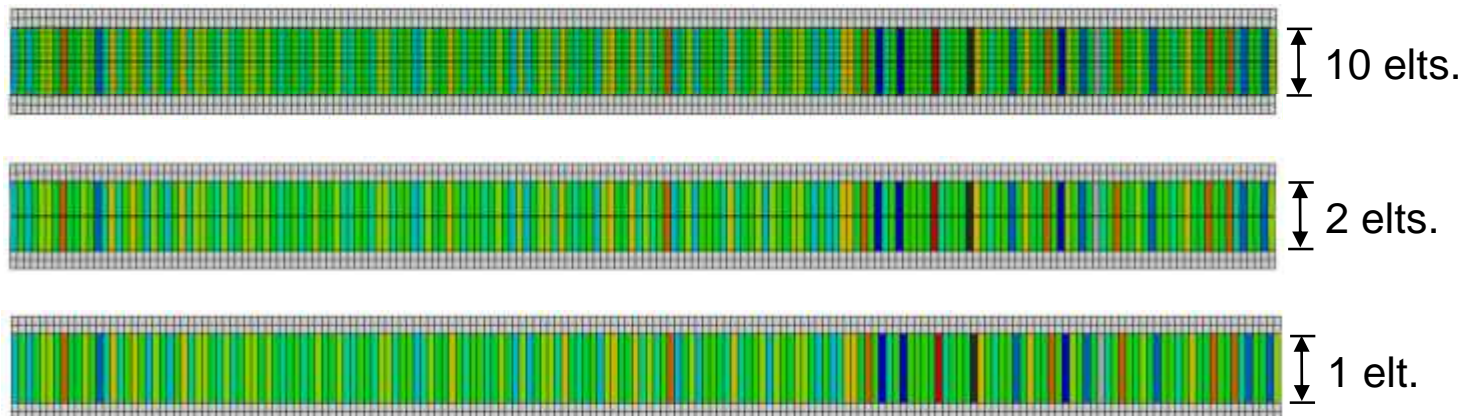
- Strength scaled by f , Fracture toughness scaled by f^2
- Constant f along each crack path



$f(x)$



Inhomogeneity applied to 3 levels of mesh refinement



Effect of Transverse Mesh Density on Crack Spacing



F Leone, 2015



Commercial finite element vendors and developers are providing more and more tools for progressive damage analysis.

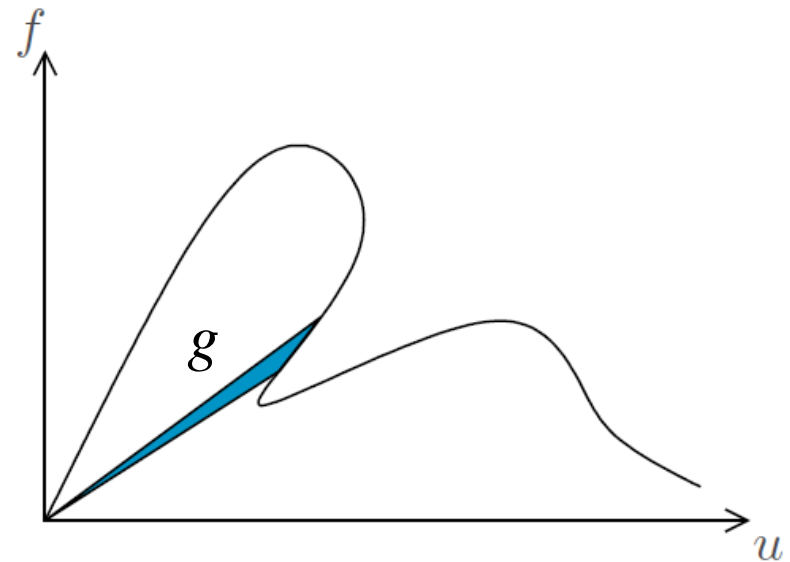
But, if the load incrementation procedures do not converge...

... more analysis tools
=
more rope!

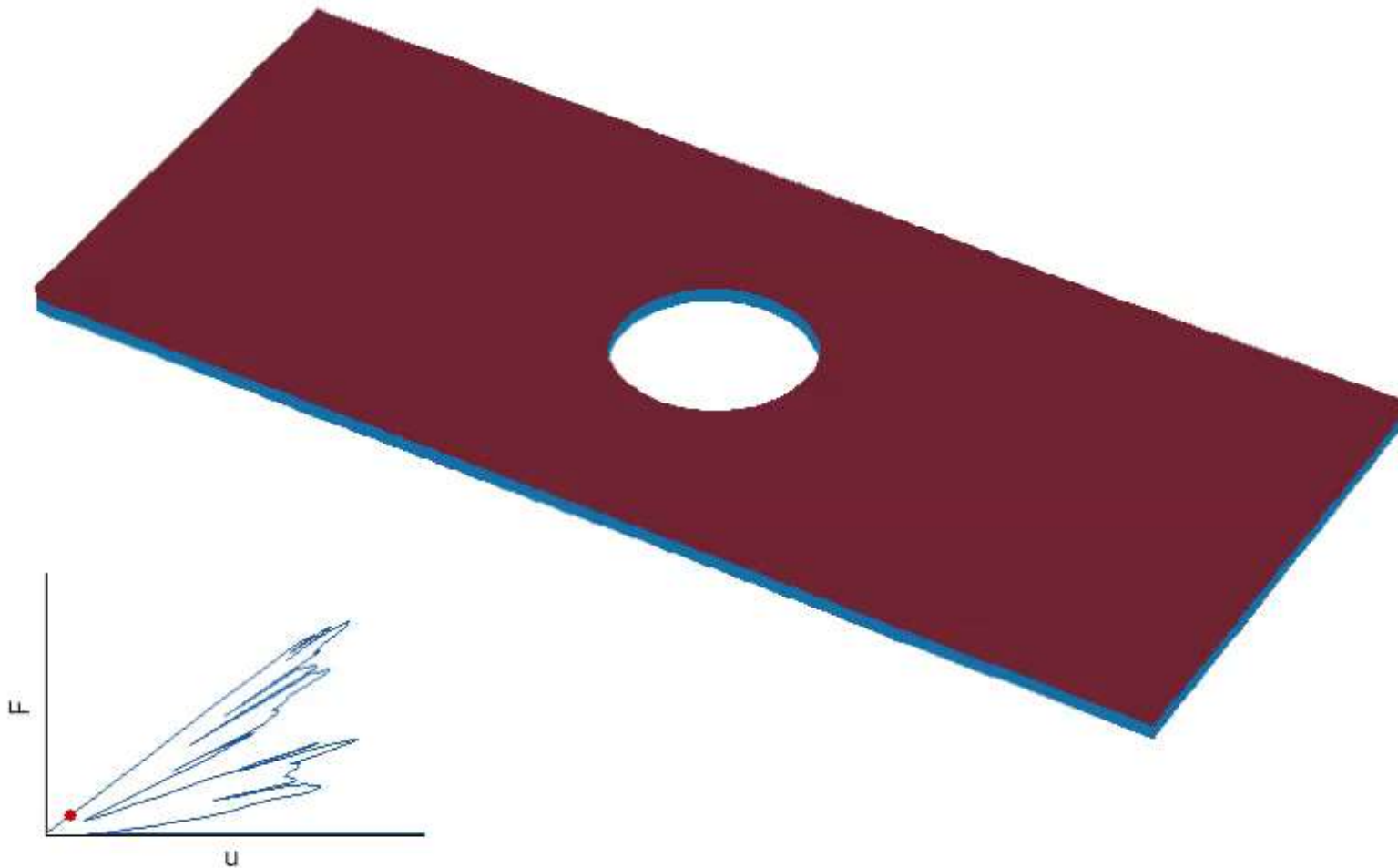


- Viscoelastic Stabilization
 - Delayed damage evolution
- Implicit dynamics or Explicit solution
- Arc-length techniques
 - Dissipation-based arc-length

Constant energy
dissipation in each
load increment

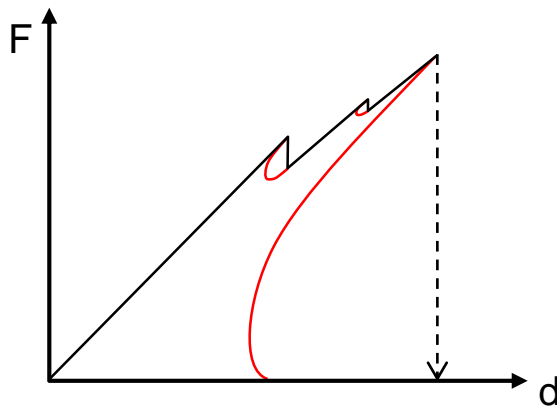


Gutiérrez, *Comm Numer Meth Eng* (2004)
Verhoosel et al. *Int J Numer Meth Eng* (2009)

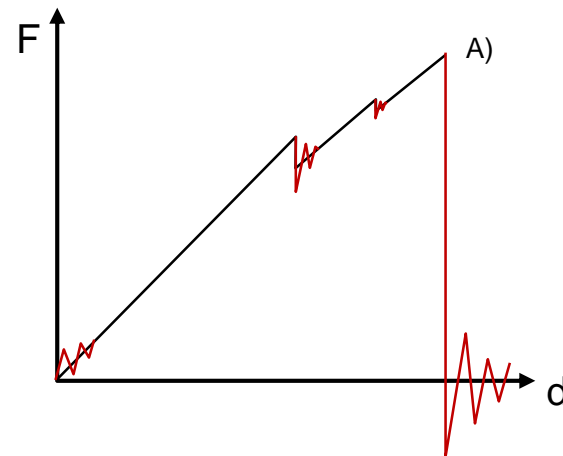


Van der Meer, *Eng Fract Mech*, 2010

- Is the QS solution physical?
- Are the dynamic effects necessary?
- Which solution provides more insight into failure modes?



Implicit



Explicit

Concluding Remarks



- A typical structural tests usually consist of three stages:
 1. QS elastic response without damage
 2. QS response with damage accumulation
 3. Dynamic collapse/rupture
- Most structural failures exhibit size effects that depend on load redistribution that occurs during the QS phases
 - Correct softening laws based on strength and toughness considerations are required
- Dynamic collapse/rupture is a result of the interaction between damage propagation and structural response
 - A stable equilibrium state often does not exist after failure under either load or displacement control
 - Onset of instability (failure) occurs when more elastic strain energy can be released by the structure than is necessary for damage propagation
 - Simulation of unstable rupture is often needed to ascertain mode of failure and to compare to test results